A semigroup-theoretical approach to the study of generalized inverses

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joint work with

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Origins of generalized inverses

Historical notes

- * E. I. Fredholm (1903) generalized inverses of integral operators;
- * D. Hilbert (1904) differential operators, A. Hurwitz (1912), and others;
- * E. H. Moore (1920 or earlier) generalized inverses of matrices (general reciprocal);
- ★ Moore's work has not attracted more attention until the 1950s;
- * A. Bjerhammar (1951) links with solutions of linear systems;
 - least-squares solutions (approximate) and minimum-norm solutions;
- * R. Penrose (1955) generalized inverses as solutions of algebraic equations;
 - Moore-Penrose equations;
 - in abstract algebraic structures semigroups, rings, Banach algebras, C*-algebras, etc.;

Applications

- ★ solving matrix equations;
- ★ solving singular differential and difference equations;
- ★ the investigation of Cesaro-Neumann iterations;
- ★ the least squares approximation;
- ★ finite Markov chains, cryptography, statistics, etc.

Moore-Penrose equations

- ★ S an involution semigroup;
- ★ $a \in S$ fixed element, x unknown taking values in S;
- ★ Moore-Penrose equations:
 - (1) axa = a
 - (2) xax = x;
 - (3) $(ax)^* = ax$
 - (4) $(xa)^* = xa$
- \star Additionally, we consider the equation
 - (5) ax = xa

γ -inverses

- ★ for $\gamma \subseteq \{1, 2, 3, 4, 5\}$, by $\langle \gamma \rangle$ we denote the system consisting of the equations (*i*), for all *i* ∈ γ ;
- * if $\langle \gamma \rangle$ has a solution, then *a* is called γ -*invertible*.
- ★ in this case, solutions of $\langle \gamma \rangle$ are called γ -*inverses* of *a*.

Terminology and notation

Terminology

{1}-inverse	g-inverse ("generalized inverse") or inner inverse
{2}-inverse	outer inverse
{1,2}-inverse	reflexive g-inverse or Thierrin-Vagner inverse
{1,3}-inverse	last-squares g-inverse
{1,4}-inverse	minimum-norm g-inverse
{1, 2, 3, 4}-inverse	Moore-Penrose inverse or MP-inverse
{1, 2, 5}-inverse	group inverse

★ When exist, the Moore-Penrose inverse and the group inverse of *a* are *unique*.

a [†]]	Moore-Penrose inverse of <i>a</i>
a# 5	group inverse of <i>a</i>
ay t	the set of all γ -inverses of a
$a\gamma_X$ i	the set of all γ -inverses of <i>a</i> contained in the set <i>X</i>
$S^{(1)}$ 1	the set of all {1}-invertible elements (<i>Reg</i> (<i>S</i>))
X• 1	the set of all idempotents contained in the set X

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Matrices with prescribed range and null-space

Range, null space, rank

- ★ $A \in \mathbb{C}^{m \times n}$ a complex matrix of type $m \times n$;
- * range or image of A

 $R(A) = \{y \in \mathbb{C}^m | Ax = y, \text{ for some } x \in \mathbb{C}^n\}$

★ *null space* or *kernel* of A

$$N(A) = \{ x \in \mathbb{C}^n \, | \, Ax = \mathbf{0} \, \}$$

★ rank(A) – the *rank* of A (the dimension of the *column space* and the *row space* of A).

Generalized inverses with prescribed range and null space

- ★ $T \subseteq \mathbb{C}^m$, $S \subseteq \mathbb{C}^n$ given subspaces, $A \in \mathbb{C}^{m \times n}$;
- ★ $A_{T,S}^{(2)}$ the {2}-inverse of A with prescribed range T and null space S (if it exists)
- * $A_{T,S}^{(1,2)}$ the {1,2}-inverse of A with prescribed range T and null space S (if it exists)

$$A^{\dagger} = A^{(2)}_{R(A^{*}),N(A^{*})} = A^{(1,2)}_{R(A^{*}),N(A^{*})} \qquad \qquad A^{\#} = A^{(2)}_{R(A),N(A)} = A^{(1,2)}_{R(A),N(A)}$$

★ A^* – the *conjugate transpose* of A

Semigroup-theoretical approach to generalized inverses

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Ring-theoretical generalizations

Generalized inverses with prescribed idempotents

- ★ D. Djordjević, Y. Wei, Communications in Algebra 33 (2005) 3051–3060 outer inverses with prescribed idempotents (xax = x and idempotents ax, xa are prescribed)
- * B. Načevska, D. Djordjević, Communications in Algebra 39 (2011) 634–646

inner inverses with prescribed idempotents (a = axa and idempotents ax, xa are prescribed)

Generalized inverses with prescribed ideals

- D. Mosić, D. Djordjević, G. Kantún-Montiel, Electronic Journal in Linear Algebra 27 (2014) 272–283
- *G. Kantún-Montiel*, Linear and Multilinear Algebra 62 (2014) 1187–1196 outer inverses with prescribed kernel ideals (left and right annihilators) outer inverses with prescribed image ideals (principal left and right ideals)

Semigroup-theoretical generalization

Semigroup of matrices $M_{\emptyset}(\mathbb{C})$

Let $M(\mathbb{C})$ be the set of *all matrices of any type* with entries in \mathbb{C} , i.e.,

$$M(\mathbb{C}) = \bigcup_{m,n\in\mathbb{N}} \mathbb{C}^{m\times n},$$

Let $M_{\emptyset}(\mathbb{C}) = M(\mathbb{C}) \cup \{\emptyset\}$, where $\emptyset \notin M(\mathbb{C})$.

For the sake of convenience, we call Ø the *empty matrix*.

The multiplication in $M_{\emptyset}(\mathbb{C})$ is defined using the standard procedure for converting a partial semigroup into a semigroup:

- * the product in $M_{\emptyset}(\mathbb{C})$ coincides with the *ordinary matrix product*, whenever it is defined;
- \star in all other cases the product is equal to the empty matrix \emptyset .

With respect to this multiplication, $M_{\emptyset}(\mathbb{C})$ is a semigroup with the zero \emptyset .

We call $M_{\emptyset}(\mathbb{C})$ the *semigroup of matrices* with entries in \mathbb{C} .

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Semigroup-theoretical generalization (cont.)

Green's equivalences in the semigroup of matrices

For any $A, B \in M(\mathbb{C})$ we have

 $\begin{array}{lll} A \mathscr{R} B &\Leftrightarrow & \mathbf{R}(A) = \mathbf{R}(B), \\ A \mathscr{L} B &\Leftrightarrow & \mathbf{N}(A) = \mathbf{N}(B), \\ A \mathscr{H} B &\Leftrightarrow & \mathbf{R}(A) = \mathbf{R}(B) \& & \mathbf{N}(A) = \mathbf{N}(B), \\ A \mathscr{D} B &\Leftrightarrow & \operatorname{rank}(A) = \operatorname{rank}(B) \end{array}$

On the other hand,

$$D_{\emptyset} = R_{\emptyset} = L_{\emptyset} = H_{\emptyset} = \{\emptyset\}.$$

Our mission

Outer inverses belonging to prescribed Green's equivalence classes

□ *M. Ćirić, P. Stanimirović, J. Ignjatović, Outer inverses in semigroups belonging to prescribed Green's equivalence classes,* to appear.

In the sequel, let *S* be a semigroup and let $a, b \in S$.

Theorem 1

An element $x \in S$ is an outer inverse of a contained in the \mathscr{R} -class R_b if and only if $x \in bS$ and xab = b.

Theorem 2 – The outer inverse in the prescribed \mathcal{R} -class

The following statements are equivalent:

- (i) there exists an outer inverse of a contained in the \mathscr{R} -class R_b ;
- (ii) there exists $u \in S$ such that b = buab;
- (iii) $b \in S^{(1)}$ and $ab \in L_b$;
- (iv) $ab \in S^{(1)}$ and $b(ab)^{(1)}ab = b$, for some (eqivalently every) $(ab)^{(1)} \in ab\{1\}$.

If these statements are true, then

 $a\{2\}_{R_b} = \{bu \mid u \in S \text{ such that } b = buab\} = \{b(ab)^{(1)} \mid (ab)^{(1)} \in ab\{1\}\}.$

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linear equation

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linear equation

Miroslav Ćirić, Predrag Stanimirović, Jelena Ignjatović

Theorem 3 - The inner inverse in the prescribed principal right ideal

The following statements are equivalent:

- (i) there exists an inner inverse of a contained in the principal right ideal R(b);
- (ii) there exists $u \in S$ such that a = abua;
- (iii) $a \in S^{(1)}$ and $ab \in R_a$;

(iv) $ab \in S^{(1)}$ and $ab(ab)^{(1)}a = a$, for some (eqivalently every) $(ab)^{(1)} \in ab\{1\}$.

If these statements are true, then

 $a\{1\}_{bS} = \{bu \mid u \in S \text{ such that } a = abua\} = \{b(ab)^{(1)} \mid (ab)^{(1)} \in ab\{1\}\}.$

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Theorem 4 – The {1,2}-inverse in the prescribed *R***-class**

The following statements are equivalent:

- (i) there exists a $\{1, 2\}$ -inverse of a contained in the \mathcal{R} -class R_b ;
- (ii) there exist $u, v \in S$ such that b = buab and a = abva;
- (iii) there exists $w \in S$ such that b = bwab and a = abwa;
- (iv) there exist $s, t \in S$ such that a = abs and b = tab;
- (v) *ab is a trace product;*

(vi) $ab \in S^{(1)}$, $ab(ab)^{(1)}a = a$ and $b(ab)^{(1)}ab = b$, for some (eqivalently every) $(ab)^{(1)} \in ab\{1\}$. If these statements are true, then

$$a\{1,2\}_{R_b} = a\{2\}_{R_b} = a\{1\}_{R(b)}.$$

Trace product (F. Pastijn, 1982)

- the product *ab* is called a *trace product* if $ab \in R_a \cap L_b$
- *Miller-Cliffords theorem*: $ab \in R_a \cap L_b \iff R_b \cap L_a$ contains an idempotent

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In the sequel, let *S* be a semigroup and let $a, d \in S$.

Mary's inverse along an element (Mary, 2011)

An element $x \in S$ is an *inverse of a along d* if any of the following two equivalent conditions holds

(M1) xad = d = dax and $x \in R(d) \cap L(d)$, (M2) xax = x and $x \mathcal{H} d$.

(M2) means that an inverse of *a* along *d* is exactly an *outer inverse of a in the Green's* \mathcal{H} -class H_d

Theorem - X. Mary (LAA, 2011), X. Mary, P. Patrício (LAMA, 2013)

The following statements are equivalent:

- (i) there exists an outer inverse of a contained in the \mathcal{H} -class H_d ;
- (ii) ad is group invertible and $ad \in L_d$;
- (iii) *da is group invertible and da* \in *R*_{*d*};
- (iv) $dad \in H_d$.

If these statements are true, then the inverse x of a along d is represented as follows:

$$x = d(ad)^{\#} = (da)^{\#}d.$$

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Another approach

From now on, let *S* be a semigroup and $a, b, c \in S$.

Drazin's (b, c)-inverse (Drazin, LAA, 2012)

An element $x \in S$ is a (b, c)-inverse of a if it satisfies

- (a) $x \in bS \cap Sc$;
- (b) xab = b and cax = c.

If *a* has a (*b*, *c*)-inverse, then it is *unique*, and in this case we say that *a* is (*b*, *c*)-*invertible*.

Theorem 5 – The outer inverse in the prescribed \mathcal{H} -class

The following two conditions for $x \in S$ *are equivalent:*

- (i) *x* is *a* (*b*, *c*)-inverse of *a*;
- (ii) *x* is an outer inverse of a contained in the \mathcal{H} -class $R_b \cap L_c$.

Drazin versus Mary

- ★ Drazin's (b, c)-inverse = Mary's inverse along d, for all triples b, c, d such that $R_b \cap L_c = H_d$.
- ★ the only difference in the way of representing Green's *H*-classes.

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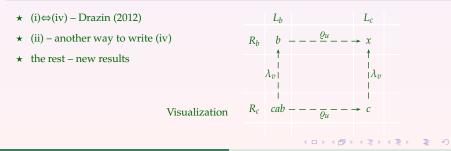
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The existence of an outer inverse in the \mathcal{H} -class $R_b \cap L_c$

Theorem 6 – *The existence theorem*

The following statements are equivalent:

- (i) there exists an outer inverse of a contained in the \mathscr{H} -class $R_b \cap L_c$ (i.e., a (b, c)-inverse);
- (ii) $cab \in R_c \cap L_b$;
- (iii) cab is {1}-invertible, $cab(cab)^{(1)}c = c$ and $b(cab)^{(1)}cab = b$, for some (equiv. all) $(cab)^{(1)} \in cab{1}$;
- (iv) there exist $u, v \in S$ such that b = vcab and c = cabu;
- (v) there exist $u, v \in S$ such that b = bucab and c = cabvc;
- (vi) there exists $w \in S$ such that b = bwcab and c = cabwc;
- (vii) there exist $u, v \in S$ such that b = buab, c = cavc and bu = vc.



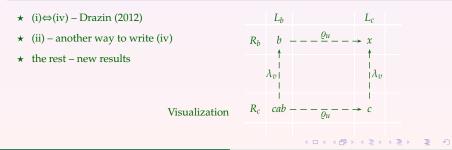
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The first representation theorem

Theorem 7 – *The first representation theorem*

If it exists, the outer inverse x of a contained in $R_b \cap L_c$ *can be represented as*

 $x = b(cab)^{(1)}c,$

for an arbitrary $(cab)^{(1)} \in cab\{1\}$, and it can also be represented as

 $x = b(ab)^{(1)} = (ca)^{(1)}c,$

for some $(ab)^{(1)} \in ab\{1\}$ and $(ca)^{(1)} \in ca\{1\}$.

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Theorem 8 – The trace factorization theorem

Let D be a \mathcal{D} -class of a semigroup S and $d \in D$. Then

- (a) For every $e \in D^{\bullet}$ there exist $u \in L_e$ and $v \in R_e$ such that d = uv, $R_d = R_u$ and $L_d = L_v$.
- (b) For every pair $u, v \in S$ such that d = uv, $R_d = R_u$ and $L_d = L_v$ there exists $e \in D^{\bullet}$ such that $u \in L_e$ and $v \in R_e$.

\star the representation $d = uv$
with $e \in D^{\bullet}$, $u \in R_d \cap L_e$ and $v \in L_d \cap R_e$ –
trace factorization of d with respect to e
(since <i>uv</i> is a trace product)
\star direct generalization of the
full-rank factorization of matrices
<i>d</i> – matrix
e – identity matrix of the same rank

	L_d	Le	
R_d	d=uv	и	
R _e	υ	е	

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\star the representation $d = uv$
with $e \in D^{\bullet}$, $u \in R_d \cap L_e$ and $v \in L_d \cap R_e$ –
trace factorization of d with respect to e
(since <i>uv</i> is a trace product)
\star direct generalization of the
full-rank factorization of matrices
<i>d</i> – matrix
e – identity matrix of the same rank

$R_d d = uv \qquad u$	
R _e v e	
K _e U t	

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Theorem 8 – The trace factorization theorem

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	L_d	Le	
<i>R</i> _d	d=uv	и	
D			
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(a)

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The second representation theorem

Theorem 9

The following statements are equivalent:

- (i) x is a (b, c)-inverse of a;
- (ii) for every $e \in D^{\bullet}$ there exist $u \in L_e \cap R_b$ and $v \in R_e \cap L_c$ such that $vau \in H_e$ and $x = u(vau)^{\#}v$;
- (iii) there exist $e \in D^{\bullet}$, $u \in L_e \cap R_b$ and $v \in R_e \cap L_c$ such that $vau \in H_e$ and $x = u(vau)^{\#}v$.

\star trace factorization		L_b	Le	L _c
of an arbitrary $d \in R_b \cap L_c$	R_b	b	и	$\begin{array}{c} x \\ d = uv \end{array}$
	R _e		e vau	υ
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The third representation theorem

Theorem 10

The following statements are equivalent:

- (i) *x is a* (*b*, *c*)-*inverse of a;*
- (ii) for every $e \in D^{\bullet}$ there exist $u \in L_e \cap R_b$ and $v \in R_e \cap L_c$ such that vau = e and x = uv;
- (iii) there exist $e \in D^{\bullet}$, $u \in L_e \cap R_b$ and $v \in R_e \cap L_c$ such that vau = e and x = uv.

★ trace factorization of the (b, c)-inverse x

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Theorem 11

The following statements are equivalent:

- (i) there exists a $\{1, 2\}$ -inverse of a contained in the \mathscr{H} -class $R_b \cap L_c$;
- (ii) there exist a $\{1, 2\}$ -inverse of a contained in R_b and a $\{1, 2\}$ -inverse of a contained in L_c ;
- (iii) there exists $u \in S$ such that b = bucab, c = cabuc and a = abuca.

If these statements are true, the {1,2}*-inverse x of a contained in the* \mathscr{H} *-class* $R_b \cap L_c$ *is represented by*

x = buc = yaz,

for an arbitrary $u \in S$ such that b = bucab, and arbitrary $y \in a\{1, 2\}_{R_b}$ and $z \in a\{1, 2\}_{L_c}$.

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Theorem 12

The following statements are equivalent:

- (i) there exists an outer inverse of a contained in the \mathscr{R} -class R_{a^*} ;
- (ii) there exists an inner inverse of a contained in the principal right ideal $R(a^*)$;
- (iii) there exists a $\{1, 2\}$ -inverse of a contained in the \mathscr{R} -class R_{a^*} ;
- (iv) *a is* {1, 4}*-invertible;*
- (v) *a is* {1, 2, 4}-*invertible;*
- (vi) there exists $u \in S$ such that $a^* = a^*uaa^*$;
- (vii) there exists $v \in S$ such that $a^* = vaa^*$;
- (viii) *aa*^{*} *is a trace product*.

If these statements are true, then

$$\begin{split} a\{1,4\} &= \{v \in S \mid a^* = vaa^*\},\\ a\{1,2,4\} &= a\{2\}_{R_{a^*}} = a\{1\}_{R(a^*)} = a\{1,2\}_{R_{a^*}} = \{a^*u \mid u \in S \text{ such that } a^* = a^*uaa^*\}\\ &= \{a^*(aa^*)^{(1)} \mid (aa^*)^{(1)} \in aa^*\{1\}\} = \{vav \mid v \in S \text{ such that } a^* = vaa^*\}. \end{split}$$

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- (i) there exists an outer inverse of a contained in the \mathscr{H} -class $R_{a^*} \cap L_{a^*}$;
- (ii) there exist an outer inverse of a contained in R_{a^*} and an outer inverse of a contained in L_{a^*} ;
- (ii) there exists an inner inverse of a contained in $R(a^*) \cap L(a^*)$;
- (iv) there exists a {1,2}-inverse of a contained in the \mathscr{H} -class $R_{a^*} \cap L_{a^*}$;
- (v) *a is* {1, 3, 4}-*invertible*;
- (vi) a is MP-invertible;
- (vii) there exists $u \in S$ such that $a^* = a^*aa^*u$;
- (viii) there exists $v \in S$ such that $a^* = va^*aa^*$;
 - (ix) there exist $u, v \in S$ such that $a^* = a^*uaa^*$ and $a^* = a^*ava^*$;
 - (x) there exist $u, v \in S$ such that $a^* = vaa^*$ and $a^* = a^*au$;
 - (xi) *a***a* and *aa** are trace products.

If these statements are true, then

$$a^{\dagger} = a^{*}(a^{*}aa^{*})^{(1)}a^{*} = (a^{*}a)^{\#}a^{*} = a^{*}(aa^{*})^{\#} = a^{*}u = va^{*} = a^{*}paqa^{*} = sat,$$

for arbitrary $(a^*aa^*)^{(1)} \in a^*aa^*\{1\}$, $u \in S$ such that $a^* = a^*aa^*u$, $v \in S$ such that $a^* = va^*aa^*$, $p, q \in S$ such that $a^* = a^*paa^*$ and $a^* = a^*aqa^*$, and $s, t \in S$ such that $a^* = saa^*$ and $a^* = a^*at$.

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The following statements are equivalent:

- (i) there exists an outer inverse of a contained in the \mathscr{H} -class $R_{a^*} \cap L_{a^*}$;
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 - (x) there exist $u, v \in S$ such that $a^* = vaa^*$ and $a^* = a^*au$;
 - (xi) *a*a and aa* are trace products.*

If these statements are true, then

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S. Crvenković (1982)

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Theorem 14

Let S be an involutive semigroup, let $a \in S$ *be an* MP-invertible element, let *D be the* \mathcal{D} -class of *S containing a and* a^* .

Let $a^* = uv$ be a trace factorization of a^* with respect to an arbitrary $e \in D^{\bullet}$. Then $vau \in H_e$ and

 $a^{\dagger} = u(vau)^{\#}v.$

Applications

Generalized inverses of complex matrices

P. Stanimirović, M. Ćirić, I. Stojanović, D. Gerontitis, Conditions for existence, representations and computation of matrix generalized inverses, COMPLEXITY Vol. 2017 (2017) Article ID 6429725, 27 pages.

computation based on representations in terms of linear equations and the well-known method for solving matrix equations of the form AXB = D

existence criteria – given in terms of ranks (e.g., rank(*CAB*) = rank(*B*) = rank(*C*))

Generalized inverses of fuzzy matrices

M. Ćirić, J. Ignjatović, The existence of generalized inverses of fuzzy matrices, in: L. Kóczy, J. Kacprzyk, J. Medina (eds.), ESCIM 2016, STUDIES IN COMPUTATIONAL INTELLIGENCE, Springer 2017, to appear.

computation based on our methods for solving equations and inequalities defined by residuated functions

Generalized inverses in residuated semigroups and quantales

 J. Ignjatović, M. Ćirić, Moore-Penrose equations in involutive residuated semigroups and involutive quantales, FILOMAT 31:2 (2017) 183–196.
a similar methodology