

STRONGLY DISTINGUISHED CONNECTIONS IN A RECURRENT K-HAMILTON SPACE

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Abstract

In the $n + mK$ dimensional differentiable manifold E^* (K-Hamilton space) special coordinate transformations are allowed. In $T^*(E^*) \otimes T^*(E^*)$ the metric tensor is given, and using the nonlinear connection $N, T(E^*)$ may be decomposed in $K + 1$ orthogonal subspaces (with respect to G): $T_H(E^*)$ and ${}_{(\alpha)}T_V(E^*), \alpha = \overline{1, K}$. In $T(E^*)$ a strongly distinguished connection is introduced in such a way that Y and $\nabla_X Y$ belong to the same subspace of $T(E^*), \forall X, Y \in T(E^*)$. The law of transformation of connection coefficients is given. For the metrical and recurrent case the connection coefficients and the torsion tensor are determined.

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1. Coordinate bases in $T(E^*)$ and $T^*(E^*)$

Let E^* be an $n + mK$ dimensional differentiable manifold. If u is one point of E^* , then in some local chart u has coordinates

$$u = ((x^i), (p_a^1), (p_a^2), \dots, (p_a^K)) = ((x^i), (p_a^\alpha)) = (x, p),$$

where $(x^i) = (\underline{x^1}, \underline{x^2}, \dots, \underline{x^n}) = (x)$, $(p_a^\alpha) = ((p_1^\alpha), \dots, (p_m^\alpha)) = (p^\alpha)$ and $a, b, c, d, e, f = \overline{1, m}, \quad i, j, h, k, l, m = \overline{1, n}, \quad \alpha, \beta, \gamma, \delta = \overline{1, K}$.

We shall consider the following transformation of a coordinate system. If $((x^{i'}), (p_a^\alpha)) = (x', p')$ are the coordinates of the same point u in the new coordinate system, then

$$(1.1) \quad \begin{aligned} (a) \quad & x^{i'} = x^{i'}(x^1, \dots, x^n) & \text{rank } [\partial x^{i'}/\partial x^i] &= n \\ (b) \quad & p_a^{\alpha'} = M_a^{\alpha'}(x^1, \dots, x^n) p_a^\alpha & \text{rank } [\partial p_a^{\alpha'}/\partial p_a^\alpha] &= m. \end{aligned}$$

The Einstein summation convention will be used for all three kinds of indices, except when the index is in brackets. If (1.1) is valid, then an inverse transformation exists

$$(1.2) \quad \begin{aligned} (a) \quad & x^i = x^i(x^{1'}, \dots, x^{n'}) \\ (b) \quad & p_a^\alpha = M_a^{\alpha'}(x^{1'}, \dots, x^{n'}) p_a^{\alpha'}. \end{aligned}$$

The natural basis $\bar{B} = \{(\partial_i), (\partial_1^a), \dots, (\partial_K^a)\}$ of $T(E^*)$ is formed by n vectors of type $\partial_i = \partial/\partial x^i$ and $m \cdot K$ vectors of type $\partial_\alpha^a = \partial/\partial p_a^\alpha$. Any vector field $X \in T(E^*)$ may be written in the form

$$(1.3) \quad X = \bar{X}^i \partial_i + \bar{X}_a^\alpha \partial_\alpha^a.$$

With respect to the coordinate transformations (1.1) and (1.2) the basic vectors of \bar{B} have the following law of transformation

$$(1.4) \quad \begin{bmatrix} \partial_i \\ \partial_1^a \\ \vdots \\ \partial_K^a \end{bmatrix} = \begin{bmatrix} \frac{\partial x^{i'}}{\partial x^i} & (\partial_i M_a^{\alpha'}) p_a^1 & \dots & (\partial_i M_a^{\alpha'}) p_a^K \\ 0 & M_a^{\alpha'} & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & M_a^{\alpha'} \end{bmatrix} \begin{bmatrix} \partial_{i'} \\ \partial_1^{\alpha'} \\ \vdots \\ \partial_K^{\alpha'} \end{bmatrix}$$

$$(1.5) \quad \begin{bmatrix} \partial_{i'} \\ \partial_1^{\alpha'} \\ \vdots \\ \partial_K^{\alpha'} \end{bmatrix} = \begin{bmatrix} \frac{\partial x^j}{\partial x^{i'}} & (\partial_{i'} M_b^{b'}) p_b^1 & \dots & (\partial_{i'} M_b^{b'}) p_b^K \\ 0 & M_b^{b'} & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & M_b^{b'} \end{bmatrix} \begin{bmatrix} \partial_j \\ \partial_1^b \\ \vdots \\ \partial_K^b \end{bmatrix}.$$

Substituting (1.5) into (1.4), we obtain

$$(1.6) \quad \begin{aligned} (a) \quad & \frac{\partial x^{i'}}{\partial x^i} \frac{\partial x^j}{\partial x^{i'}} = \delta_i^j & (b) \quad & M_a^{(\alpha)} M_b^{(\alpha)'} = \delta_b^a \\ (c) \quad & (\partial_{i'} M_b^{b'}) p_b^\alpha \frac{\partial x^{i'}}{\partial x^i} + (\partial_i M_a^{a'}) p_a^\alpha M_b^{a'} = 0. \end{aligned}$$

(1.6c) is the consequence of (1.4) and (1.6b).

2. Adapted bases in $T(E^*)$ and $T^*(E^*)$

From (1.4) and (1.5) it is obvious that ∂_i and $\partial_{i'}$ are not transformed as tensors, so we introduce a new, the so-called adapted basis $B = \{(\delta_i), (\partial_1^a), \dots, (\partial_K^a)\}$ of $T(E^*)$, where by definition

$$(2.1) \quad \delta_i = \partial_i - N_{ai}^\alpha(x, p) \partial_\alpha^a$$

and $N_{ai}^\alpha(x, p)$ are the coefficients of the nonlinear connection. Under coordinate transformation (1.1) and (1.2), they transform in the following way:

$$(2.2) \quad \begin{aligned} (a) \quad & N_{a'i'}^\alpha(x', p') = M_{a'}^a \frac{\partial x^i}{\partial x^{i'}} N_{ai}^\alpha(x, p) - p_a^\alpha \frac{\partial M_{a'}^a}{\partial x^i} \frac{\partial x^i}{\partial x^{i'}} \\ (b) \quad & N_{bj}^\alpha(x, p) = M_b^{b'} \frac{\partial x^{j'}}{\partial x^j} N_{b'j'}^\alpha(x', p') + p_a^\alpha M_b^{a'} \frac{\partial M_{a'}^a}{\partial x^j}. \end{aligned}$$

Any vector field $X \in T(E^*)$ in the adapted basis B is given by

$$(2.3) \quad X = X^i \delta_i + X_a^\alpha \partial_\alpha^a.$$

The coordinates of the vector X given by (2.3) and the elements of basis B are transformed as tensor in the following way:

$$(2.4) \quad \begin{aligned} (a) \quad & \delta_i = \frac{\partial x^{i'}}{\partial x^i} \delta_{i'} & (b) \quad & \partial_\alpha^a = M_{a'}^a(x) \partial_{\alpha'}^{a'} \\ (c) \quad & X^i = \frac{\partial x^i}{\partial x^{i'}} X^{i'} & (d) \quad & X_a^\alpha = M_a^{a'}(x') X_{a'}^\alpha. \end{aligned}$$

From (1.3) and (2.3) we obtain the relation between the coordinates of the field X in the bases \bar{B} and B . They are connected by the formula

$$X^i = \bar{X}^i, \quad X_a^\alpha = \bar{X}_a^\alpha + N_{ai}^\alpha \bar{X}^i$$

The subspace of $T(E^*)$ spanned by $\{\delta_i\}$ shall be denoted by $T_H(E^*)$ (horizontal part) and the subspace spanned by $\{\partial_\alpha^a\}$ by ${}_{(\alpha)}T_V(E^*)$ (the vertical α part). So we have

$$T(E^*) = T_H(E^*) \oplus T_V(E^*),$$

where

$$T_V(E^*) = \sum_{\alpha=1}^K {}_{(\alpha)}T_V(E^*),$$

$$\dim T_H(E^*) = n, \quad \dim {}_{(\alpha)}T_V(E^*) = m.$$

$X^i\delta_i$ is the horizontal and $X_a^\alpha\partial_\alpha^a$ the vertical part of the field X .

Now (2.3) may be written in the form

$$X = X_H + X_V, \quad X_H = X^i\delta_i, \quad X_V = X_a^\alpha\partial_\alpha^a.$$

Let us consider the dual tangent space of E^* , the space $T^*(E^*)$. The natural basis in $T^*(E^*)$ is

$$\begin{aligned} \overline{B}^* &= \{dx^1, \dots, dx^n, dp_1^1, \dots, dp_m^1, \dots, dp_1^K, \dots, dp_m^K\} \\ &= \{dx^i, dp_a^1, \dots, dp_a^K\}. \end{aligned}$$

From (1.1) we obtain

$$(2.5) \quad (a) \quad dx^{i'} = \frac{\partial x^{i'}}{\partial x^i} dx^i$$

$$(b) \quad dp_{a'}^\alpha = \frac{\partial M_{a'}^\alpha(x)}{\partial x^i} p_a^\alpha dx^i + M_{a'}^\alpha(x) dp_a^\alpha.$$

From (2.5b) it is obvious that dp_a^α are not transformed as tensors, so we introduce a new basis $B^* = \{(dx^1), (\delta p_a^1), \dots, (\delta p_a^K)\}$, where

$$(2.6) \quad \delta p_a^\alpha = dp_a^\alpha + N_{a'}^\alpha(x, p) dx^{i'}.$$

By the coordinate transformation (1.1) the bases \overline{B}^* and B^* are related by (2.5a) and

$$(2.7) \quad (a) \quad \delta p_a^\alpha = M_a^{\alpha'}(x') \delta p_{a'}^\alpha, \quad (b) \quad \delta p_{a'}^\alpha = M_{a'}^\alpha(x) \delta p_a^\alpha.$$

The proof of (2.7) is obtained using (2.6) and (2.2). Any field $w \in T^*(E^*)$ can be written in the bases and B^* and \bar{B}^* in the following way

$$(2.8) \quad w = \bar{w}_i dx^i + \bar{w}_\alpha^a dp_\alpha^a = w_i dx^i + w_\alpha^a \delta p_\alpha^a,$$

where

$$(2.9) \quad w_i = \bar{w}_i - N_{a_i}^\alpha \bar{w}_\alpha^a, \quad \bar{w}_\alpha^a = w_\alpha^a.$$

The subspace of $T^*(E^*)$ spanned by $\{(dx^i)\}$ shall be denoted by $T_H^*(E^*)$ and the subspace spanned by $\{(\delta p_\alpha^a)\}$ by ${}_\alpha T_V^*(E^*)$.

So we have

$$T^*(E^*) = T_H^*(E^*) \oplus T_V^*(E^*),$$

where

$$T_V^*(E^*) = \sum_{\alpha=1}^K {}_\alpha T_V^*(E^*).$$

Now (2.8) may be written in the form

$$w = w_H + w_V, \quad w_H = w_i dx^i, \quad w_V = w_\alpha^a \delta p_\alpha^a.$$

If $\{(dx^i), (\delta p_\alpha^1), \dots, (\delta p_{\alpha'}^K)\}$ and $\{(dx^{i'}), (\delta p_{\alpha'}^1), \dots, (\delta p_{\alpha'}^K)\}$ are two bases in $T^*(E^*)$ related by (2.5a) and (2.7) then any $w \in T^*(E^*)$ satisfies the relation

$$(2.10) \quad w = w_i dx^i + w_\alpha^a \delta p_\alpha^a = w_{i'} dx^{i'} + w_{\alpha'}^{a'} \delta p_{\alpha'}^{a'}.$$

Substituting $dx^{i'}$ from (2.5a) and $\delta p_{\alpha'}^{a'}$ from (2.7b) into (2.10) and comparing the coefficients besides basis vectors, we obtain

$$(2.11) \quad w_i = w_{i'} \frac{\partial x^{i'}}{\partial x^i}, \quad w_\alpha^a = M_{\alpha'}^{(\alpha)a} w_{\alpha'}^{a'}.$$

By a straightforward calculation we can prove

Proposition 2.1. *The adapted bases $\{(\delta_i), (\partial_1^a), \dots, (\partial_K^a)\}$ and $\{(dx^i), (\delta p_\alpha^1), \dots, (\delta p_{\alpha'}^K)\}$ are dual to each other, i.e.*

$$\begin{aligned} \langle \delta_i, dx^j \rangle &= \delta_i^j & \langle \delta_i, \delta p_\alpha^a \rangle &= 0 \\ \langle \partial_\alpha^a, dx^j \rangle &= 0 & \langle \partial_\alpha^a, \delta p_b^\beta \rangle &= \delta_\alpha^a \delta_\beta^b. \end{aligned}$$

3. Tensor Fields on E^*

a) A horizontal tensor field t_H has the local representation:

$$t_H = t^{i_1 \dots i_p}_{j_1 \dots j_q}(x, p) \delta_{i_1} \otimes \dots \otimes \delta_{i_p} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_q}.$$

It is defined on

$$\underbrace{T_H(E^*) \otimes \dots \otimes T_H(E^*)}_{p \text{ times}} \otimes \underbrace{T_H^*(E^*) \otimes \dots \otimes T_H^*(E^*)}_{q \text{ times}}.$$

By changing the coordinates given by (1.1) and (1.2), the coordinates of the field t_H have the following transformation law

$$t^{i'_1 \dots i'_p}_{j'_1 \dots j'_q} = \frac{\partial x^{i'_1}}{\partial x^{i_1}} \dots \frac{\partial x^{i'_p}}{\partial x^{i_p}} \frac{\partial x^{j_1}}{\partial x^{j'_1}} \dots \frac{\partial x^{j_q}}{\partial x^{j'_q}}, \quad t^{i_1 \dots i_p}_{j_1 \dots j_q}.$$

b) The α vertical tensor field $(\alpha)t_V$ has the local representation

$$(\alpha)t_V = (\alpha) t^{\alpha \dots \alpha a_1 \dots a_r}_{b_1 \dots b_s \alpha \dots \alpha} \partial_\alpha^{b_1} \otimes \dots \otimes \partial_\alpha^{b_s} \otimes \delta p_{a_1}^\alpha \otimes \dots \otimes \delta p_{a_r}^\alpha$$

(not summing over α).

$(\alpha)t_V$ is defined on

$$\underbrace{(\alpha)T_V(E^*) \otimes \dots \otimes (\alpha)T_V(E^*)}_{s \text{ times}} \otimes \underbrace{(\alpha)T_V^*(E^*) \otimes \dots \otimes (\alpha)T_V^*(E^*)}_{r \text{ times}}.$$

By changing the coordinates of type (1.1) and (1.2) the coordinates of the field $(\alpha)t_V$ given above have the following transformation law

$$\begin{aligned} (\alpha)t^{\alpha' \dots \alpha' a'_1 \dots a'_r}_{\alpha \dots \alpha b'_1 \dots b'_s} &= \\ &= (\alpha) t^{\alpha \dots \alpha a_1 \dots a_r}_{\alpha \dots \alpha b_1 \dots b_s} M_{a_1}^{\alpha'} \dots M_{a_r}^{\alpha'} M_{b_1}^{b'_1} \dots M_{b_s}^{b'_s}. \end{aligned}$$

c) A vertical tensor field t_V on $T_V(E^*) \otimes T_V^*(E^*)$ has the form

$$t_V = t_{a_1 \beta}^{\alpha b_1} \partial_\alpha^{a_1} \otimes \delta p_{b_1}^\beta$$

(summing over α and β).

The coordinate transformation of tensor t_V is given by

$$t_{a'_1 \beta}^\alpha = t_{a_1 \beta}^\alpha M_{a'_1}^{(\alpha)} M_{b_1}^{(\beta)}.$$

d) A tensor field t on

$$\underbrace{T_H(E^*) \otimes \dots \otimes T_H(E^*)}_p \otimes \underbrace{T_H^*(E^*) \otimes \dots \otimes T_H^*(E^*)}_q \otimes \underbrace{T_V(E^*) \otimes \dots \otimes T_V(E^*)}_s \otimes \underbrace{T_V^*(E^*) \otimes \dots \otimes T_V^*(E^*)}_r$$

is given by

$$t = t^{i_1 \dots i_p}_{j_1 \dots j_q} \beta_1 \dots \beta_s a_1 \dots a_r (x, p) \delta_{i_1} \otimes \dots \otimes \delta_{i_p} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_q} \otimes \partial_{\beta_1}^{b_1} \otimes \dots \otimes \partial_{\beta_s}^{b_s} \otimes \delta p_{a_1}^{\alpha_1} \otimes \dots \otimes \delta p_{a_r}^{\alpha_r}.$$

The summation goes over all the indices.

The coordinate transformation of the above tensor is given by

$$t = t^{i'_1 \dots i'_p}_{j'_1 \dots j'_q} \beta_1 \dots \beta_s a'_1 \dots a'_r = t^{i_1 \dots i_p}_{j_1 \dots j_q} \beta_1 \dots \beta_s a_1 \dots a_r \frac{\partial x^{i'_1}}{\partial x^{i_1}} \dots \frac{\partial x^{i'_p}}{\partial x^{i_p}} \frac{\partial x^{j_1}}{\partial x^{j'_1}} \dots \frac{\partial x^{j_q}}{\partial x^{j'_q}} M_{b'_1}^{(\beta_1)} \dots M_{b'_s}^{(\beta_s)} M_{a_1}^{(\alpha_1)} \dots M_{a_r}^{(\alpha_r)}$$

The order of spaces $T_H(E^*)$, $T_H^*(E)$, ${}_{(\alpha)}T_V(E^*)$ and $T_V^*(E^*)$ can be taken arbitrary. It has an influence on the order of indices of tensor t which is defined on their tensor product.

4. Metric tensor in the K-Hamilton space

In the space $T^*(E^*) \otimes T^*(E^*)$ the metric tensor G with respect to the basis $\{(dx^i), (\delta p_a^1, \dots, (\delta p_a^K)\}$ has the form

$$(4.1) \quad G = [(dx^i)(\delta p_a^1)\dots(\delta p_a^K)].$$

$$\begin{bmatrix} [g_{ij}] & [g_{i1}^b] & \dots & [g_{iK}^b] \\ [g_{1j}^a] & [g_{11}^{ab}] & \dots & [g_{1K}^{ab}] \\ \vdots & \vdots & \vdots & \vdots \\ [g_{Kj}^a] & [g_{K1}^{ab}] & \dots & [g_{KK}^{ab}] \end{bmatrix} \otimes \begin{bmatrix} dx^j \\ \delta p_b^1 \\ \vdots \\ \delta p_b^K \end{bmatrix}.$$

The matrices $[g_{ij}]$, $[g_{i\beta}^b]$, $[g_{\alpha j}^a]$ and $[g_{\alpha\beta}^{ab}]$ have the format $n \times n$, $n \times m$, $m \times n$ and $m \times m$ respectively. As G is a tensor, its coordinates in the new coordinate system (x', p') are transformed in the following way:

$$(4.2) \quad \begin{aligned} a) \quad g_{i'j'} &= g_{ij} \frac{\partial x^i}{\partial x^{i'}} \frac{\partial x^j}{\partial x^{j'}} & b) \quad g_{\alpha j'}^{a'} &= g_{\alpha j}^a M_a^{a'} \frac{\partial x^j}{\partial x^{j'}} \\ c) \quad g_{i'\beta}^{b'} &= g_{i\beta}^b \frac{\partial x^i}{\partial x^{i'}} M_b^{b'} & d) \quad g_{\alpha\beta}^{a'b'} &= g_{\alpha\beta}^{ab} M_a^{a'} M_b^{b'} \end{aligned}$$

We shall suppose that G is a symmetric, positive definite tensor field of rank $n + mK$. From the symmetry it follows that

$$g_{ji} = g_{ij} \quad g_{i\beta}^b = g_{\beta i}^b \quad g_{\alpha\beta}^{ab} = g_{\beta\alpha}^{ba}.$$

The "covariant" coordinates of the field $X = X^i \delta_i + X_\alpha^a \partial_\alpha^a$ are given by

$$(4.3) \quad X_i = g_{ij} X^j + g_{i\alpha}^a X_\alpha^a, \quad X_\alpha^a = g_{\alpha i}^a X^i + g_{\alpha\beta}^{ab} X_b^\beta.$$

The inverse matrix of G (appearing in (4.1)) is given by

$$\begin{bmatrix} [g^{jk}] & [g_c^{j1}] & \dots & [g_c^{jK}] \\ [g_b^{1k}] & [g_{bc}^{11}] & \dots & [g_{bc}^{1K}] \\ \vdots & \vdots & \vdots & \vdots \\ [g_b^{Kk}] & [g_{bc}^{K1}] & \dots & [g_{bc}^{KK}] \end{bmatrix}$$

The matrices $[g^{jk}]$, $[g_c^{j\gamma}]$, $[g_c^{\gamma k}]$ and $[g_{bc}^{\beta\gamma}]$ have the format $n \times n$, $n \times m$, $m \times m$ and $m \times m$ respectively. Now we have

$$(4.4) \quad \begin{aligned} a) \quad g_{ij} g^{jk} + g_{i\beta}^b g_b^{\beta k} &= \delta_i^k & b) \quad a_{\alpha j}^a g_c^{j\gamma} + g_{\alpha\beta}^{ab} g_{bc}^{\beta\gamma} &= \delta_c^\alpha \delta_\alpha^\gamma \\ c) \quad g_{ij} g_c^{j\gamma} + g_{i\beta}^b g_{bc}^{\beta\gamma} &= 0 & d) \quad g_{\alpha j}^a g^{jk} + g_{\alpha\beta}^{ab} g_b^{\beta k} &= 0. \end{aligned}$$

The contravariant coordinates of $w = w_i dx^i + w_\alpha^\alpha \delta p_\alpha^\alpha$ are given by

$$(4.5) \quad w^i = g^{ij} w_j + g^{i\alpha} w_\alpha^\alpha \quad w_\alpha^\alpha = g^{j\alpha} w_j + g_{ab}^{\alpha\beta} w_\beta^b.$$

Using (2.4), (2.11) and (4.2) it can be shown that following transformation laws are valid:

$$X_{i'} = X_i \frac{\partial x^i}{\partial x^{i'}} \quad X_{\alpha'}^{\alpha} = X_\alpha^\alpha M_{\alpha'}^{\alpha(\alpha)}$$

$$w_{i'} = w_i \frac{\partial x^i}{\partial x^{i'}} \quad w_{\alpha'}^\alpha = w_\alpha^\alpha M_{\alpha'}^{\alpha(\alpha)}.$$

If the k -Hamilton function $H(X, p)$ is given in the space E^* , then the metric tensor G can be defined in the following way:

$$g_{ij}(x, p) = g_{ij}(x) \quad g_{i\beta}^b = 0 \quad g_{\alpha j}^a = 0$$

$$g_{\alpha\beta}^{ab} = 2^{-1} \partial_\alpha^a \partial_\beta^b H^2(x, p) \quad \forall \alpha, \beta = \overline{1, K},$$

where $g_{ij}(x)$ is some metric tensor defined on M and M is the π^* projection of E^*

$$\pi^*(E^*) = M, \quad \pi^*((x^i), (p_a^1), \dots, (p_a^K)) = (x^i).$$

We can not define

$$g_{i\beta}^b(x, p) = 2^{-1} \delta_i \partial_\beta^b H^2(x, p), \quad g_{ij}(x, p) = 2^{-1} \delta_i \delta_j H^2(x, p),$$

because the above quantities are not transformed as tensor.

Using the metric G determined by (4.1) we define the scalar product (X, Y) of fields $X, Y \in T(E^*)$ by

$$(4.6) \quad (X, Y) = g_{ij} X^i Y^j + g_{i\beta}^b X^i Y_b^\beta + g_{\alpha j}^a X_\alpha^\alpha Y^j + g_{\alpha\beta}^{ab} X_\alpha^\alpha Y_b^\beta.$$

Then length of $X, |X|$ is defined by $|X|^2 = (X, X)$ and $\cos\theta$, where θ is the angle between X and Y by

$$(4.7) \quad \cos \theta = \frac{(X, Y)}{|X| |Y|}.$$

When $\cos \theta = 0$, we say that the fields X and Y are orthogonal to each other. For the horizontal field X_H we have

$$X_H = X^i \delta_i, \quad |X_H|^2 = g_{ij} X^i X^j$$

and for vertical vector X_V we have

$$X_V = X_a^\alpha \partial_\alpha^a \quad |X_V|^2 = g_{\alpha\beta}^{ab} X_a^\alpha X_b^\beta.$$

For the field ${}_{(\alpha)}X_V \in {}_{(\alpha)}T_V(E^*)$ we have

$${}_{(\alpha)}X_V = X_a^\alpha \partial_\alpha^a, \quad |{}_{(\alpha)}X_V|^2 = g_{\alpha\alpha}^{ab} X_a^\alpha X_b^\alpha \text{ (not summing over } \alpha \text{)}.$$

Theorem 4.1. *The necessary and sufficient conditions that the subspaces $T_H(E^*)$, ${}_{(1)}T_V(E^*)$, ..., ${}_{(K)}T_V(E^*)$ of $T(E^*)$ should be orthogonal to each other with respect to the metric tensor G , are*

$$[g_{i\beta}^b] = 0, \quad [g_{\alpha j}^a] = 0, \quad \forall \alpha, \beta = \overline{1, K} \quad \alpha \neq \beta.$$

Definition 4.1. *The differentiable manifold E^* in which the coordinate transformations of type (1.1) and (1.2) are allowed, supplied with the nonlinear connection N (see (2.2)) and the metric tensor G (given by (4.1)) is called the K -Hamilton space.*

5. Strongly distinguished connection in $T(E^*)$

The distinguished connection ∇ or d -connection in the K -Hamilton space in [15], [9], [16] and others is defined as a function $\nabla : (X, Y) \rightarrow \nabla_X Y$; $X, Y, \nabla_X Y \in T(E^*)$ for which, besides the usual conditions for the linear connection, the following restrictions hold

$$(5.1) \quad (a) \quad \nabla_X Y_H \in T_H(E^*) \quad (b) \nabla_X Y_V \in T_V(E^*)$$

$$\forall X \in T(E^*), \forall Y_H \in T_H(E^*) \quad \text{and} \quad \forall Y_V \in T_V(E^*).$$

The strongly distinguished or s.d. - connection is the linear connection for which (5.1 a) and (5.2)

$$(5.2) \quad \nabla_X {}_{(\alpha)}Y_V \in {}_{(\alpha)}T_V(E^*)$$

hold.

Definition 5.1. The strongly distinguished connection ∇ in $T(E^*)$ is the linear connection defined by

$$(5.3) \quad (a) \quad \nabla_{\delta_i} \delta_j = F_{ij}^k \delta_k, \quad b) \quad \nabla_{\delta_i} \partial_\alpha^a = F_{ci}^{(\alpha)a} \partial_\alpha^c$$

$$(c) \quad \nabla_{\partial_\alpha^a} \delta_j = C_j^{ka} \delta_k \quad d) \quad \nabla_{\partial_\alpha^a} \partial_\beta^b = C_{c\alpha}^{b a} \partial_\beta^c.$$

In (5.3b) and (5.3d) there is no summation over α and β respectively.

Proposition 5.1. If $X, Y \in T(E^*)$, where X is given by (2.3) and $Y = Y^j \delta_j + Y_b^\beta \partial_\beta^b$, then

$$(5.4) \quad \nabla_X Y = (Y_{|i}^j X^i + Y^j |_\alpha^a X_\alpha^a) \delta_j + (Y_{b|i}^\beta X^i + Y_b^\beta |_\alpha^a X_\alpha^a) \partial_\beta^b,$$

where

$$(a) \quad Y_{|i}^j = \delta_i Y^j + F_{ki}^j Y^k$$

$$(b) \quad Y^j |_\alpha^a = \partial_\alpha^a Y^j + C_{k\alpha}^{ja} Y^k$$

$$(5.5) \quad (c) \quad Y_{b|i}^\beta = \delta_i Y_b^\beta + F_{bi}^d Y_d^\beta$$

$$(d) \quad Y_b^\beta |_\alpha^a = \partial_\alpha^a Y_b^\beta + C_{b\alpha}^{d a} Y_d^\beta.$$

Proposition 5.2. If $((x^i), (p_\alpha^a))$ and $((x^{i'}), (p_{\alpha'}^a))$ are two coordinate systems connected by (1.1) and (1.2) then

$$(5.6) \quad \nabla_{X'} Y' = \nabla_X Y$$

iff $Y_{|i}^j$, $Y^j |_\alpha^a$, $Y_{b|i}^\beta$ and $Y_b^\beta |_\alpha^a$ are transformed as tensors, i.e.

$$Y_{|i'}^{j'} = Y_{|i}^j (\partial_{i'} x^i) (\partial_j x^{j'}) \quad Y^{j'} |_{\alpha'}^{a'} = Y^j |_\alpha^a (\partial_j x^{j'}) M_\alpha^{a'}$$

$$Y_{b'|i'}^\beta = Y_{b|i}^\beta M_{b'}^b (\partial_{i'} x^i) \quad Y_b^\beta |_{\alpha'}^{a'} = Y_b^\beta |_\alpha^a M_b^b M_\alpha^{a'}$$

or equivalently iff the s.d.-connection coefficients have the following law of transformation:

$$(a) \quad F_{ji}^k = F_{j'i'}^{k'}(\partial_j x^{j'}) (\partial_{k'} x^k) (\partial_i x^{i'}) + (\partial_i \partial_j x^{k'}) (\partial_{k'} x^k)$$

$$(b) \quad F_{ci}^b = F_{c'i'}^{b'} M_{b'}^b M_c^{c'} (\partial_i x^{i'}) + (\partial_i M_{b'}^b) M_c^{c'}$$

(5.7)

$$(c) \quad C_{ja}^{k\alpha} = C_{j'a'}^{k'\alpha'} (\partial_j x^{j'}) (\partial_{k'} x^k) M_{a'}^{\alpha}$$

$$(d) \quad C_{c\alpha}^{b a} = C_{c'\alpha'}^{b' a'} M_{b'}^b M_c^{c'} M_{a'}^{\alpha}$$

Proof. The proof is obtained by direct calculation using (5.4) - (5.6), (2.1) and (2.4).

It follows from (5.7) that the F 's which appear in (5.7a) and (5.7b) are transformed as connection coefficients, and the two C 's in (5.7c) and (5.7d) as tensors.

The torsion tensor $T(X, Y)$ for the s.d.-connection, is as usual, given by

$$(5.8) \quad T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]. \quad \square$$

Theorem 5.1. *In the k -Hamilton space the torsion tensor for the s.d. - connection has the form*

$$(5.9) \quad \begin{aligned} T(X, Y) = & (F_{ki}^j - F_{ik}^j) X^i Y^k \delta_j + C_k^{j a} X_a^\alpha Y^k \delta_j - C_i^{j b} X^i Y_b^\beta \delta_j + \\ & C_{b\alpha}^{(\beta) d a} X_a^\alpha Y_d^\beta \partial_\beta^b - C_{c\beta}^{(\alpha) a} X_a^\alpha Y_b^\beta \partial_\alpha^c + \\ & (\partial_i N_{aj}^\alpha - \partial_j N_{ai}^\alpha + N_{bj}^\beta \partial_\beta^b N_{ai}^\alpha - N_{bi}^\beta \partial_\beta^b N_{aj}^\alpha) X^i Y^j \partial_\alpha^a + \\ & \left[F_{bi}^d Y_b^\beta - (\partial_\alpha^a N_{bi}^\beta) Y_a^\alpha \right] X^i \partial_\beta^b + \\ & \left[(\partial_\alpha^a N_{bj}^\beta) X_a^\alpha - F_{bj}^d X_d^\beta \right] Y^j \partial_\beta^b. \end{aligned}$$

Proof. The proof is obtained by direct calculation using (5.3), (5.4), (5.5) and (5.8). \square

If we suppose that the nonlinear connection N is such that N_{bi}^β is the function only of (x) and $(p^\beta) = (p_1^\beta, \dots, p_m^\beta)$ for $\forall \beta = \overline{1, K}$, then the three

last lines in (5.9) have the form

$$\begin{aligned}
 & (\partial_i N_{aj}^\alpha - \partial_j N_{ai}^\alpha + N_{bj}^{(\alpha)} \partial_{(\alpha)}^b N_{bi}^\alpha - N_b^{(\alpha)} \partial_{(\alpha)}^b N_{aj}^\alpha) X^i Y^j \partial_\alpha^a + \\
 (5.10) \quad & + (F_{bi}^d - \partial_{(\beta)}^d N_{bi}^{(\beta)}) X^i Y_d^\beta \partial_\beta^b + \\
 & + (\partial_{(\beta)}^d N_{bj}^{(\beta)} - F_{bj}^d) X_d^\beta Y^j \partial_\beta^b.
 \end{aligned}$$

The Einstein summation convention is not meant on (α) and (β) . \square

Theorem 5.2. *In the K -Hamilton space the torsion tensor for the s.d. - connection is identically equal to zero iff*

$$(a) \quad \partial_\alpha^a N_{\beta i}^b = 0 \quad \text{for } \forall \alpha \neq \beta$$

$$(b) \quad F_{ki}^j - F_{ik}^j = 0,$$

$$(c) \quad C_k^{j a} = 0$$

$$(5.11)$$

$$(d) \quad C_{b\alpha}^{d a} - C_{b\alpha}^{a d} = 0$$

$$(e) \quad C_{b\gamma}^{a c} = 0 \quad \text{for } \forall \alpha \neq \gamma$$

$$(f) \quad \partial^i N_{aj}^\alpha - \partial_j N_{ai}^\alpha - N_{bi}^{(\alpha)} \partial_{(\alpha)}^b N_{aj}^\alpha + N_{bj}^{(\alpha)} \partial_{(\alpha)}^b N_{ai}^\alpha = 0$$

$$(g) \quad F_{bi}^d = \partial_{(\beta)}^d N_{bi}^\beta.$$

Proof. The proof follows from (5.9) and (5.10). \square

Theorem 5.3. *In the K -Hamilton space the torsion free s.d. - connection has the following properties*

$$(a) \quad \nabla_{\delta_i} \delta_j = \nabla_{\delta_j} \delta_i, \quad \nabla_{X_H} Y_H \in T_H(E^*)$$

$$(b) \quad \nabla_{(\alpha)X_V} (\beta)Y_V = 0 \quad \forall \alpha \neq \beta$$

$$(5.12)$$

$$(c) \quad \nabla_{\partial_\alpha^a} \partial_\alpha^b = \nabla_{\partial_\alpha^b} \partial_\alpha^a \quad \nabla_{(\alpha)X_V} Y_V \in (\alpha)T_V(E^*)$$

$$(d) \quad \nabla_{(\alpha)X_V} Y_H = 0.$$

If instead of (5.11 a) the stronger condition

$$(5.13) \quad \partial_\alpha^a N_{\beta i}^b = 0 \quad \forall \alpha \neq \beta = \overline{1, m}$$

is satisfied, then besides (5.12) the torsion free s.d. - connection has the property $\nabla_{X_H}(\alpha)Y_V = 0$.

From Theorems 5.2 and 5.3 follows the following

Theorem 5.4. *In the torsion free K-Hamilton space for which condition (5.13) holds the strongly distinguished connection reduces to the following form:*

$$\nabla_{\delta_i} \delta_j = F_{ji}^k \delta_k, \quad F_{ij}^k = F_{ji}^k, \quad \nabla_{\delta_i} \partial_\alpha^a = 0, \quad \nabla_{\partial_\alpha^a} \delta_j = 0,$$

$$(5.14) \quad \nabla_{\partial_\alpha^a} \partial_\beta^b = 0 \quad \text{for } \alpha \neq \beta, \quad \nabla_{\partial_\alpha^a} \partial_\alpha^b = C_c^{b a} \partial_\alpha^c, \quad C_c^{b a} = C_c^{a b},$$

6. Strongly distinguished connection in $T^*(E^*)$

The connection ∇ defined on $T(E^*)$ by (5.3) induces a connection ∇^* on $T^*(E^*)$ which will also be denoted by ∇ . For the field X defined by (2.9) and w defined by (2.14) we have

$$(6.1) \quad \nabla_X w = \nabla_{X^i \delta_i + X_\alpha^a \partial_\alpha^a} (w_j dx^j + w_\beta^b \delta p_\beta^b).$$

Definition 6.1. *The connection ∇ on $T^*(E^*)$ is defined by*

$$(a) \quad \nabla_{\delta_i} dx^j = \tilde{F}_k^j dx^k \quad (b) \quad \nabla_{\delta_i} \delta p_b^\beta = \tilde{F}_{bi}^{c(\beta)} \delta p_c^\beta$$

(6.2)

$$(c) \quad \nabla_{\partial_\alpha^a} dx^j = \tilde{C}_k^j \partial_\alpha^a dx^k \quad (d) \quad \nabla_{\partial_\alpha^a} \delta p_b^\beta = \tilde{C}_{b\alpha}^{c(\beta)} \delta p_c^\beta.$$

Proposition 6.1. *If $X \in T(E^*)$ and $w \in T^*(E^*)$, then*

$$(6.3) \quad \nabla_X w = (w_{j|i} X^i + w_j |_\alpha X_\alpha^a) dx^j + (w_{\beta|i} X^i + w_\beta^b |_\alpha X_\alpha^a) \delta p_b^\beta,$$

where

$$(a) \quad w_{j|i} = \delta_i w_j + \tilde{F}_j^k w_k$$

$$(b) \quad w_j|_\alpha^a = \partial_\alpha^a w_j + \tilde{C}_j^\alpha{}^{ka} w_k$$

$$(6.4)$$

$$(c) \quad w_{\beta|i}^b = \delta_i w_\beta^b + \tilde{F}^{b\ c}{}_{ci} w_\beta^c$$

$$(d) \quad w_\beta^b|_\alpha^a = \partial_\alpha^a w_\beta^b + \tilde{C}^{b\ a}{}_{c\alpha} w_\beta^c.$$

Proof. Substituting (6.2) into (6.1) and using the linearity of connection ∇ we obtain (6.3) and (6.4). \square

Using the properties of the linear connection ∇ and relations (4.1) and (6.2), the following relations are fulfilled:

$$\begin{aligned} \nabla_X G &= (g_{ij|k} X^k + g_{ij} |_\gamma^c X_c^\gamma) dx^i \otimes dx^j + \\ & (g_{i\beta|k}^b X^k + g_{i\beta}^b |_\gamma^c X_c^\gamma) dx^i \otimes \delta p_b^\beta + \\ (6.5) \quad & (g_{\alpha j|k}^a X^k + g_{\alpha j}^a |_\gamma^c X_c^\gamma) \delta p_\alpha^a \otimes dx^j + \\ & (g_{\alpha\beta|k}^{ab} X^k + g_{\alpha\beta}^{ab} |_\gamma^c X_c^\gamma) \delta p_\alpha^a \otimes \delta p_b^\beta, \end{aligned}$$

where

$$(a) \quad g_{ij|k} = \delta_k g_{ij} + g_{hj} \tilde{F}_i^h{}^k + g_{ih} \tilde{F}_j^h{}^k$$

$$(b) \quad g_{ij} |_\gamma^c = \partial_\gamma^c g_{ij} + g_{hj} \tilde{C}_i^h{}^c{}_\gamma + g_{ih} \tilde{C}_j^h{}^c{}_\gamma$$

$$(c) \quad g_{i\beta|k}^b = \delta_k g_{i\beta}^b + g_{h\beta}^b \tilde{F}_{ik}^h + g_{i\beta}^d \tilde{F}^{b\ c}{}_{dk}{}^{(\beta)}$$

$$(6.6)$$

$$(d) \quad g_{i\beta}^b |_\gamma^c = \partial_\gamma^c g_{i\beta}^b + g_{h\beta}^b \tilde{C}_{i\gamma}^{hc} + g_{i\beta}^d \tilde{C}^{(\beta)bc}{}_{d\gamma}$$

$$(e) \quad g_{\alpha\beta|k}^{ab} = \delta_k g_{\alpha\beta}^{ab} + g_{\alpha\beta}^{db} \tilde{F}_{dk}^a{}^{(\alpha)} + g_{\alpha\beta}^{ad} \tilde{F}^{b\ c}{}_{dk}{}^{(\alpha)}$$

$$(f) \quad g_{\alpha\beta}^{ab} |_\gamma^c = \partial_\gamma^c g_{\alpha\beta}^{ab} + g_{\alpha\beta}^{db} \tilde{C}_{d\gamma}^{ac}{}^{(\alpha)} + g_{\alpha\beta}^{ab} \tilde{C}^{(\beta)bc}{}_{d\gamma}.$$

Definition 6.2. The K -Hamilton space will be called recurrent if there exists a field $\lambda(x, p) = \lambda_k(x, p)dx^k + \lambda_\gamma^c(x, p)\delta p_\gamma^c$, such that

$$\begin{aligned}
 g_{ij|k} &= \lambda_k g_{ij} & g_{ij|_\gamma}^c &= \lambda_\gamma^c g_{ij} \\
 g_{i\beta|k}^b &= \lambda_k g_{i\beta}^b & g_{i\beta|_\gamma}^{bc} &= \lambda_\gamma^c g_{i\beta}^b \\
 (6.7) \quad g_{\alpha j|k}^a &= \lambda_k g_{\alpha j}^a & g_{\alpha j|_\gamma}^{ac} &= \lambda_\gamma^c g_{\alpha j}^a \\
 g_{\alpha\beta|k}^{ab} &= \lambda_k g_{\alpha\beta}^{ab} & g_{\alpha\beta|_\gamma}^{abc} &= \lambda_\gamma^c g_{\alpha\beta}^{ab}.
 \end{aligned}$$

The K -Hamilton space will be called a metric space if

$$\begin{aligned}
 (6.8) \quad g_{ij|k} &= 0 & g_{ij|_\gamma}^c &= 0 & g_{i\beta|k}^b &= 0 & g_{i\beta|_\gamma}^{bc} &= 0 \\
 g_{\alpha j|k}^a &= 0 & g_{\alpha j|_\gamma}^{ac} &= 0 & g_{\alpha\beta|k}^{ab} &= 0 & g_{\alpha\beta|_\gamma}^{abc} &= 0.
 \end{aligned}$$

Theorem 6.1. In the recurrent and in the metric K -Hamilton spaces the strongly distinguished connection ∇ defined on $T(E^*)$ by (5.3) and on $T^*(E^*)$ by (6.2) is compatible with the raising and lowering of the indices by the metric tensor G iff following conditions are satisfied

$$\begin{aligned}
 (6.9) \quad \tilde{F}_k^j{}^i &= -F_k^j{}^i & \tilde{F}_{bi}^{(\beta)c} &= -F_{bi}^{(\beta)c}, \\
 \tilde{C}_k^j{}^a &= -C_k^j{}^a & \tilde{C}_{b\alpha}^{(\beta)c} &= -C_{b\alpha}^{(\beta)c}.
 \end{aligned}$$

Proof. The proof is obtained from (4.3), (6.6), (6.7), (6.4) and (5.5). It is similar to the proof of Theorem 6.1 in [8]. \square

Theorem 6.2. In the recurrent K -Hamilton space the coordinates of the inverse metric tensor satisfy the following relations

$$\begin{aligned}
 (6.10) \quad g_{|k}^{ij} &= -\lambda_k g^{ij}, & g_{b|k}^{i\beta} &= -\lambda_k g_{b}^{i\beta}, & g_{db|k}^{\delta\beta} &= -\lambda_k g_{db}^{\delta\beta} \\
 g^{ij|_\gamma} &= -\lambda_\gamma^c g^{ij}, & g_{b|_\gamma}^{i\beta} &= -\lambda_\gamma^c g_{b}^{i\beta}, & g_{db|_\gamma}^{\delta\beta} &= -\lambda_\gamma^c g_{db}^{\delta\beta}.
 \end{aligned}$$

Proof. The proof follows from (4.4) and is the same as the proof of Theorem 6.2 in [8.] \square

To avoid confusion in the application of the Einstein summation convention in the case when more than two indices are equal, we introduce the following notation:

$$F_{\alpha dk}^{a\delta} = \begin{cases} F_{dk}^{(\alpha)a} & \text{for } \alpha = \delta \\ 0 & \text{for } \alpha \neq \delta \end{cases}$$

$$C_{\alpha d\gamma}^{a\delta c} = \begin{cases} C_{d\gamma}^{(\alpha)c} & \text{for } \alpha = \delta \\ 0 & \text{for } \alpha \neq \delta \end{cases}$$

Using the above notation the raising and lowering of the middle index of the connection coefficients are given by the following formulae:

(6.11)

$$\begin{bmatrix} F_{ijk} \\ F_{i\alpha k}^a \end{bmatrix} = \begin{bmatrix} g_{ij} & g_{j\delta}^d \\ g_{\alpha h}^a & g_{\alpha\delta}^{ad} \end{bmatrix} \begin{bmatrix} F_{ik}^h \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} F_{ik}^h \\ 0 \end{bmatrix} = \begin{bmatrix} g^{hj} & g_a^{h\alpha} \\ g_d^{\delta j} & g_{d\alpha}^{\delta\alpha} \end{bmatrix} \begin{bmatrix} F_{ijk} \\ F_{i\alpha k}^a \end{bmatrix}$$

$$\begin{bmatrix} F_{\alpha ik}^a \\ F_{\alpha\beta k}^{ab} \end{bmatrix} = \begin{bmatrix} g_{ih} & g_{i\delta}^c \\ g_{\delta h}^b & g_{\beta\gamma}^{bc} \end{bmatrix} \begin{bmatrix} 0 \\ F_{\alpha ck}^{a\gamma} \end{bmatrix} \Leftrightarrow \begin{bmatrix} 0 \\ F_{\alpha ck}^{a\delta} \end{bmatrix} = \begin{bmatrix} g^{hi} & g_b^{h\beta} \\ g_d^{\delta i} & g_{db}^{\delta\beta} \end{bmatrix} \begin{bmatrix} F_{\alpha ik}^a \\ F_{\alpha\beta k}^{ab} \end{bmatrix}$$

$$\begin{bmatrix} C_{ij\gamma}^c \\ C_{i\alpha\gamma}^{ac} \end{bmatrix} = \begin{bmatrix} g_{jl} & g_{j\delta}^d \\ g_{\alpha l}^a & g_{\alpha\delta}^{ad} \end{bmatrix} \begin{bmatrix} C_{i\gamma}^{lc} \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} C_{i\gamma}^{hc} \\ 0 \end{bmatrix} = \begin{bmatrix} g^{hj} & g_a^{h\alpha} \\ g_d^{\delta j} & g_{d\alpha}^{\delta\alpha} \end{bmatrix} \begin{bmatrix} C_{ij\gamma}^c \\ C_{i\alpha\gamma}^{ac} \end{bmatrix}$$

$$\begin{bmatrix} C_{\alpha i\gamma}^{ac} \\ C_{\alpha\beta\gamma}^{abc} \end{bmatrix} = \begin{bmatrix} g_{ih} & g_{i\delta}^e \\ g_{\beta h}^b & g_{\beta\delta}^{be} \end{bmatrix} \begin{bmatrix} 0 \\ C_{\alpha e\gamma}^{acc} \end{bmatrix} \Leftrightarrow \begin{bmatrix} 0 \\ C_{\alpha d\gamma}^{a\delta c} \end{bmatrix} = \begin{bmatrix} g^{hi} & g_b^{h\beta} \\ g_d^{\delta i} & g_{bd}^{\delta\beta} \end{bmatrix} \begin{bmatrix} C_{\alpha i\gamma}^{ac} \\ C_{\alpha\beta\gamma}^{abc} \end{bmatrix}$$

The above equations are well defined because they are compatible with (4.4)

Using (6.11), (6.6) may be written in the following form:

- (a) $g_{ij|k} = \delta_k g_{ij} - F_{ijk} - F_{jik}$
- (b) $g_{ij|_\gamma}^c = \partial_\gamma^c g_{ij} - C_{ij\gamma}^c - C_{ji\gamma}^c$
- (6.12)
- (c) $g_{i\beta|k}^b = \delta_k g_{i\beta}^b - F_{i\beta k}^b - F_{\beta ik}^b$
- (d) $g_{i\beta|_\gamma}^{bc} = \partial_\gamma^c g_{i\beta}^b - C_{i\beta\gamma}^{bc} - C_{\beta i\gamma}^{bc}$

$$(e) \quad g_{\alpha\beta|k}^{ab} = \delta_k g_{\alpha\beta}^{ab} - F_{\alpha\beta k}^{ab} - F_{\beta\alpha k}^{ba}$$

$$(f) \quad g_{\alpha\beta|\gamma}^{ab|c} = \partial_\gamma^c g_{\alpha\beta}^{ab} - C_{\alpha\beta\gamma}^{abc} - C_{\beta\alpha\gamma}^{bac}.$$

7. Strongly distinguished connection coefficients in the recurrent K -Hamilton space

Theorem 7.1. *In the recurrent K -Hamilton space supplied with the metric tensor G , arbitrary torsion tensor T , the strongly distinguished connection coefficients are determined by (7.1) - (7.8):*

$$(7.1) \quad 2F_{ijk} = (\delta_k g_{ij} + \delta_i g_{jk} - \delta_j g_{ki}) - (\lambda_k g_{ij} + \lambda_i g_{jk} - \lambda_j g_{ki}) + A$$

where

$$A = (F_{ijk} - F_{kji}) + (F_{kij} - F_{jik}) + (F_{ikj} - F_{jki}) =$$

$$= g_j^h (F_{ik}^h - F_{ki}^h) + g_{ih} (F_{kj}^h - F_{jk}^h) + g_{kh} (F_{ij}^h - F_{ji}^h).$$

$$(7.2) \quad 2F_{i\alpha k}^a = (\delta_k g_{i\alpha}^a + \delta_i g_{\alpha k}^a - \partial_\alpha^a g_{ik}) -$$

$$- (\lambda_k g_{\alpha i}^a + \lambda_i g_{\alpha k}^a - \lambda_\alpha^a g_{ik}) + B,$$

$$B = (F_{i\alpha k}^a - F_{k\alpha i}^a) - (F_{\alpha ki}^a - C_{ik\alpha}^a) - (F_{\alpha ik}^a - C_{ki\alpha}^a) +$$

$$= g_{\alpha h}^a (F_{ik}^h - F_{ki}^h) - (g_{k\gamma}^c F_{\alpha ci}^{a\gamma} - g_{kh} C_{i\alpha}^{ha}) -$$

$$- (g_{i\gamma}^c F_{\alpha ck}^{a\gamma} - g_{ik} C_k^{ha}).$$

$$(7.3) \quad 2F_{\alpha ik}^a = (\delta_k g_{\alpha i}^a + \delta_\alpha^a g_{ik} - \delta_i g_{k\alpha}^a) -$$

$$- (\lambda_k g_{\alpha i}^a + \lambda_\alpha^a g_{ik} - \lambda_i g_{k\alpha}^a) - B.$$

$$(7.4) \quad 2F_{\alpha\beta k}^{ab} = (\delta_k g_{\alpha\beta}^{ab} + \partial_\alpha^a g_{\beta k}^b - \partial_\beta^b g_{k\alpha}^a) -$$

$$- (\lambda_k g_{\alpha\beta}^{ab} + \lambda_\alpha^a g_{\beta k}^b - \lambda_\beta^b g_{k\alpha}^a + C,$$

where

$$C = (F_{\alpha\beta k}^{ab} - C_{k\beta\alpha}^{ba}) - (F_{\beta\alpha k}^{ba} - C_{k\alpha\beta}^{ab}) + (C_{\alpha k\beta}^{ab} - C_{\beta k\alpha}^{ba}) =$$

$$\begin{aligned}
&= (g_{\beta\gamma}^{bc} F_{\alpha ck}^{a\gamma} - g_{\beta k}^b C_{k\alpha}^{ha}) - (g_{\alpha\gamma}^{ac} F_{\beta ck}^b - g_{\alpha h}^a C_{k\beta}^{hb}) + g_{k\epsilon}^e (C_{\alpha\epsilon\beta}^{a\epsilon b} - C_{\beta\epsilon\alpha}^{b\epsilon a}) \\
(7.5) \quad &2C_{ij\alpha}^a = (\partial_\alpha^a g_{ij} + \delta_i g_{j\alpha}^a - \delta_j g_{\alpha i}^a) - \\
&\quad - (\lambda_\alpha^a g_{ij} + \lambda_i g_{j\alpha}^a - \lambda_j g_{\alpha i}^a) + D,
\end{aligned}$$

where

$$\begin{aligned}
D &= (F_{i\alpha j}^a - F_{j\alpha i}^a) + (F_{\alpha ij}^a - C_{ji\alpha}^a) - (F_{\alpha ji}^a - C_{ij\alpha}^a) - \\
&\quad - g_{\alpha h}^a (F_{ij}^h - F_{ji}^h) + (g_{i\gamma}^c F_{\alpha c j}^{a\gamma} - g_{ih} C_{j\alpha}^{ha}) - \\
&\quad - (g_{j\gamma}^c F_{\alpha c i}^{a\gamma} - g_{jh} C_{i\alpha}^{ha}). \\
(7.6) \quad &2C_{k\alpha\beta}^{ab} = (\partial_\beta^b g_{k\alpha}^a + \delta_k g_{\alpha\beta}^{ab} - \partial_\alpha^a g_{\beta k}^b) - \\
&\quad - (\lambda_\beta^b g_{k\alpha}^a + \lambda_k g_{\alpha\beta}^{ab} - \partial_\alpha^a g_{\beta k}^b) - E,
\end{aligned}$$

where

$$\begin{aligned}
E &= (F_{\alpha\beta k}^{ab} - C_{k\beta\alpha}^{ba}) + (F_{\beta\alpha k}^{ba} - C_{k\alpha\beta}^{ab}) + (C_{\alpha k\beta}^{ab} - C_{\beta k\alpha}^{ba}) = \\
&= (g_{\beta\gamma}^{bc} F_{\alpha ck}^{a\gamma} - g_{\beta h}^b C_{k\alpha}^{ha}) + (g_{\alpha\gamma}^{ac} F_{\beta ck}^{b\gamma} - g_{\alpha h}^a C_{k\beta}^{hb}) + g_{k\epsilon}^e (C_{\alpha\epsilon\beta}^{a\epsilon b} - C_{\beta\epsilon\alpha}^{b\epsilon a}) \\
(7.7) \quad &2C_{\alpha k\beta}^{ab} = (\partial_\beta^b g_{\alpha k}^a + \partial_\alpha^a g_{k\beta}^b - \delta_k g_{\beta\alpha}^{ba} - \\
&\quad - (\lambda_\beta^b g_{\alpha k}^a + \lambda_\alpha^a g_{k\beta}^b - \lambda_k g_{\beta\alpha}^{ba}) + E \\
(7.8) \quad &2C_{\alpha\beta\gamma}^{abc} = (\partial_\gamma^c g_{\alpha\beta}^{ab} + \partial_\alpha^a g_{\beta\gamma}^{bc} - \partial_\beta^b g_{\gamma\alpha}^{ca}) - \\
&\quad - (\lambda_\gamma^c g_{\alpha\beta}^{ab} + \lambda_\alpha^a g_{\beta\gamma}^{bc} - \lambda_\beta^b g_{\gamma\alpha}^{ca}) + F,
\end{aligned}$$

where

$$F = (C_{\alpha\beta\gamma}^{abc} - C_{\gamma\beta\alpha}^{cba}) + (C_{\alpha\gamma\beta}^{acb} - C_{\beta\gamma\alpha}^{bca}) + (C_{\gamma\alpha\beta}^{cab} - C_{\beta\alpha\gamma}^{bac}).$$

Proof. The proof follows from (6.7), (6.11) and (6.12). \square

In (7.1) - (7.9) the expressions A, B, C, D, E, F and G are functions of torsion tensor T and the nonlinear connection N . The connection coefficients in the K recurrent Hamilton space can be determined using an arbitrary tensor. In the usual terminology, that the space is torsion free when $T(X, Y) = 0 \forall X, Y \in T(E^*)$ is used, then we have

Theorem 7.2. *In the torsion free recurrent K -Hamilton space, supplied with the metric tensor G , the strongly distinguished connection coefficients are determined by (7.1) - (7.8) where A, B, C, D, E and F have the following value:*

$$\begin{aligned}
 (7.9) \quad & A = 0, \\
 & B = -(g_{k(\alpha)}^c \partial_\alpha^a N_{ci}^{(\alpha)} + g_{i(\alpha)}^c \partial_\alpha^a N_{ck}^{(\alpha)}), \\
 & C = g_{\beta k(\alpha)}^{bc} \partial_\alpha^a N_{ck}^{(\alpha)} - g_{\alpha(\beta)}^{ac} \partial_\beta^b N_{ck}^{(\beta)}, \\
 & D = g_{i(\alpha)}^c \partial_\alpha^a N_{cj}^{(\alpha)} - g_{j(\alpha)}^c \partial_\alpha^a N_{ci}^{(\alpha)}, \\
 & E = g_{\beta(\alpha)}^{bc} \partial_\alpha^a N_{ck}^{(\alpha)} - g_{\alpha(\beta)}^{ac} \partial_\beta^b N_{ck}^{(\beta)}
 \end{aligned}$$

and $\delta_i N_{aj}^\alpha - \delta_j N_{ai}^\alpha = 0$ (which follows from (5.11 f)).

Proof. The proof follows from Theorem 7.1 and Theorem 7.2. \square

If in (7.1) - (7.8) the field $\lambda = \lambda_k dx^k + \lambda_\alpha^\alpha \delta p_\alpha^\alpha$ is equal to zero, then the recurrent K -Hamilton space becomes a K -Hamilton space supplied with a strongly distinguished metric connection.

Theorem 7.3. *In the torsion free K -Hamilton space supplied with the metric tensor G , the strongly distinguished metric connection coefficients are given by*

$$\begin{aligned}
 (a) \quad & 2F_{ijk} = (\delta_k g_{ij} + \delta_i g_{jk} - \delta_j g_{ki}) \\
 (b) \quad & 2F_{i\alpha k}^a = (\delta_k g_{i\alpha}^a + \delta_i g_{\alpha k}^a - \partial_\alpha^a g_{ik}) - (g_{k(\alpha)}^c \partial_\alpha^a N_{ci}^{(\alpha)} + g_{i(\alpha)}^c \partial_\alpha^a N_{ck}^{(\alpha)}) \\
 (c) \quad & 2F_{\alpha ik}^a = (\delta_k g_{\alpha i}^a + \partial_\alpha^a g_{ik} - \delta_i g_{k\alpha}^a) + (g_{k(\alpha)}^c \partial_\alpha^a N_{ci}^{(\alpha)} + g_{i(\alpha)}^c \partial_\alpha^a N_{cj}^{(\alpha)}) \\
 (d) \quad & 2F_{\alpha\beta k}^{ab} = (\delta_k g_{\alpha\beta}^{ab} + \partial_\alpha^a g_{\beta k}^b - \partial_\beta^b g_{k\alpha}^a) + (g_{\beta(\alpha)}^{bc} \partial_\alpha^a N_{ck}^{(\alpha)} - g_{\alpha(\beta)}^{ac} \partial_\beta^b N_{ck}^{(\beta)}) \\
 (7.10) \quad & \\
 (e) \quad & 2C_{ij\alpha}^a = (\partial_\alpha^a g_{ij} + \delta_i g_{j\alpha}^a - \delta_j g_{\alpha i}^a) + (g_{i(\alpha)}^c \partial_\alpha^a N_{cj}^{(\alpha)} - g_{j(\alpha)}^c \partial_\alpha^a N_{ci}^{(\alpha)}) \\
 (f) \quad & 2C_{k\alpha\beta}^{ab} = (\partial_\beta^b g_{k\alpha}^a + \delta_k g_{\alpha\beta}^{ab} - \partial_\alpha^a g_{\beta k}^b) - (g_{\beta(\alpha)}^{bc} \partial_\alpha^a N_{ck}^{(\alpha)} + g_{\alpha(\beta)}^{ac} \partial_\alpha^a N_{ck}^{(\beta)}) \\
 (g) \quad & 2C_{\alpha k\beta}^a = (\partial_\beta^b g_{\alpha k}^a + \partial_\alpha^a g_{k\beta}^b - \delta_k g_{\beta\alpha}^{ba}) + (g_{\beta(\alpha)}^{bc} \partial_\alpha^a N_{ck}^{(\alpha)} + g_{\alpha(\beta)}^{ac} \partial_\beta^b N_{ck}^{(\beta)}) \\
 (h) \quad & 2C_{\alpha\beta\gamma}^{abc} = (\partial_\gamma^c g_{\alpha\beta}^{ab} + \partial_\alpha^a g_{\beta\gamma}^{bc} - \partial_\beta^b g_{\gamma\alpha}^{ca})
 \end{aligned}$$

$$\delta_i N_{aj}^\alpha - \delta_j N_{ai}^\alpha = 0.$$

Proof. The proof follows from Theorem 7.1 and Theorem 7.2. \square

Theorem 7.4. *In the torsion free metric K – Hamilton space in which $T_H(E^*)$ is orthogonal to $T_V(E^*)$, i.e. where the metric tensor G has the property $[g_{k\alpha}^a] = 0 \ \forall \alpha = \overline{1, K}$ the strongly distinguished connection coefficients have the form*

- (a) $2F_{ijk} = (\delta_k g_{ij} + \delta_i g_{jk} - \delta_j g_{ki})$
 - (b) $2F_{i\alpha k}^a = -\partial_\alpha^a g_{ik}$
 - (c) $2F_{\alpha ik}^a = \partial_\alpha^a g_{ik}$
 - (d) $2F_{\alpha\beta k}^{ab} = \delta_k g_{\alpha\beta}^{ab} + g_{\beta(\alpha)}^{b\ c} \partial_\alpha^a N_{ck}^{(\alpha)} - g_{\alpha(\beta)}^{a\ c} \partial_\beta^b N_{ck}^{(\beta)}$
- (7.11)
- (e) $2C_{ij\alpha}^a = \partial_\alpha^a g_{ij}$
 - (f) $2C_{k\alpha\beta}^{ab} = \delta_k g_{\alpha\beta}^{ab} - (g_{\beta(\alpha)}^{b\ c} \partial_\alpha^a N_{ck}^{(\alpha)} + g_{\alpha(\beta)}^{a\ c} \partial_\beta^b N_{ck}^{(\beta)})$
 - (g) $2C_{\alpha k\beta}^{ab} = -\delta_k g_{\beta\alpha}^{ba} + g_{\beta(\alpha)}^{b\ c} \partial_\alpha^a N_{ck}^{(\alpha)} + g_{\alpha(\beta)}^{a\ c} \partial_\beta^b N_{ck}^{(\beta)}$
 - (h) $2C_{\alpha\beta\gamma}^{abc} = \partial_\gamma^c g_{\alpha\beta}^{ab} + \partial_\alpha^a g_{\beta\gamma}^{bc} - \partial_\beta^b g_{\gamma\alpha}^{ca}$.

Proof. The proof follows from (7.10) and the condition $[g_{k\alpha}^a] = 0$ for $\forall \alpha = \overline{1, K}$ \square .

It is obvious that in (7.11)

$$F_{\alpha ih}^a = -F_{i\alpha h}^a \quad C_{k\alpha\beta}^{ab} = -C_{\alpha k\beta}^{ab}.$$

In the recurrent K-Hamilton space in which $T_H(E^*)$ is orthogonal to $T_V(E^*)$ i.e. where the metric tensor has the property $[g_{i\alpha}^a] = 0$ for $\forall \alpha \overline{1, K}$, from (6.11) we get

- (a) $F_i^h{}^k = g^{hj} F_{ijh}$
- (b) $0 = g_{ad}^{\alpha\delta} F_{i\alpha k}^a$
- (c) $0 = g^{hi} F_{\alpha ik}^a$
- (d) $F^{\alpha}{}^a{}_{dk} = g^{\alpha\beta}{}_{db} F_{\alpha\beta k}^{ab}$

(7.12)

(e) $C_{i\gamma}^{hc} = g^{hj} C_{ij\gamma}^c$

(f) $0 = g_{da}^{\delta\alpha} C_{i\alpha\gamma}^{ac}$

(g) $0 = g^{hi} C_{\alpha i\gamma}^{a,c}$

(h) $C_{d\gamma}^{a,c} = g_d^{(\alpha)\beta} C_{\alpha\beta\gamma}^{abc}$.

The strongly distinguished connection coefficients which appear on the right-hand side of (7.12) for the torsion free, metric K-Hamilton space are determined by (7.11).

For the torsion free strongly distinguished connection for which $(\partial_\alpha^a N_{bk}^\beta = 0 \forall \alpha, \beta = \overline{1, \bar{K}}$ the relation (5.14) holds. These relations may be obtained for the above case also from (7.11) and (7.12).

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