

OSCILLATION PROPERTIES OF A CLASS OF SECOND ORDER EQUATIONS WITH VARIABLE COEFFICIENTS¹

Zornitza Petrova²

Abstract. We establish sufficient conditions for oscillation of the following equations:

$$z''(t) + \sum_{i=0}^n \theta_i(t)z'(t - \tau_i) + \sum_{k=0}^{\tilde{n}} \beta_k(t)z(t - \sigma_k) + G(z''(t), z'(t), z(t)) = F(t).$$

We suppose that $n, \tilde{n} \in \mathbf{N}$, $\tau_i \geq 0, \forall i = \overline{0, n}$ and $\sigma_k \geq 0, \forall k = \overline{0, \tilde{n}}$ are given constants as well as $T \geq 0$ is a large enough constant such that all the functions $\{\theta_i(t)\}_{i=0}^n, \{\beta_k(t)\}_{k=0}^{\tilde{n}}$ and $F(t)$ are of the class $C([T, \infty); \mathbf{R})$. Also, $G(z''(t), z'(t), z(t)) \in C([T, \infty)^3; \mathbf{R})$. We obtain two types of results: the first is concerned with the monotonicity of the solutions, and the second one is a sufficient condition for the distributions of their zeros.

AMS Mathematics Subject Classification (2000): 34C10, 34A30, 34A40

Key words and phrases: Oscillation, monotonicity

1. Introduction

In general, differential equations appear from the proper mathematical models and the most popular of them come from physics. Both ordinary and partial differential equations of second order attract the attention of many specialists of different areas.

The present paper treats the oscillation behavior of the equation:

$$(1) \quad z''(t) + \sum_{i=0}^n \theta_i(t)z'(t - \tau_i) + \sum_{k=0}^{\tilde{n}} \beta_k(t)z(t - \sigma_k) + G(z''(t), z'(t), z(t)) = F(t),$$

which is a natural generalization of the following one:

$$(2) \quad Az''(t) + \sum_{i=1}^n \theta_i z'(t - \tau_i) + \sum_{k=1}^{\tilde{n}} \beta_k z(t - \sigma_k) + Bz(t) = F(t)$$

since all the coefficients in (2) are given constants. Also, the delays are non-negative constants both in (1) and (2).

¹This paper was partially supported by the organizers of the 12th Serbian Mathematical Congress

²Faculty of Applied Mathematics and Informatics, Technical University of Sofia, 8 Kl. Ohridski Blvd., Sofia-1000, Bulgaria e-mail: zap@tu-sofia.bg

2. Preliminary result

Recently, Petrova [4] established two types of oscillational results for (2). The first one is about the absence of both eventually positive and monotonically non-decreasing solutions of (2) as well as of eventually negative and monotonically non-increasing solutions of (2). There we stated the following assumptions:

$$(3) \quad A > 0 \quad \text{and} \quad B > 0;$$

$$(4) \quad \theta_i \geq 0, \quad \tau_i \geq 0, \quad \forall i = \overline{1, n}, \quad n \in \mathbf{N}, \quad \tau = \max_{1 \leq i \leq n} \tau_i$$

$$(5) \quad \text{and} \quad \beta_k \geq 0, \quad \sigma_k \geq 0, \quad \forall k = \overline{1, \tilde{n}}, \quad \tilde{n} \in \mathbf{N}, \quad \sigma = \max_{1 \leq k \leq \tilde{n}} \sigma_k$$

for the first type of sufficient conditions for oscillation, which are concerned with the monotonicity of the solutions.

The second type of oscillational results in [4] are sufficient conditions for the distributions of the zeros of the following particular case of (2):

$$(6) \quad Az''(t) + \theta z'(t) + \sum_{k=1}^{\tilde{n}} \beta_k z(t - \sigma_k) + Bz(t) = F(t).$$

More exactly, we found a sequence of semiopen intervals, which consist of at least one zero of every solution of (6), where the assumptions (3) and (5) hold again, but (4) is replaced with a new one:

$$(7) \quad \theta \in \mathbf{R} \quad \text{and} \quad 4AB > \theta^2.$$

Moreover, in the paper [4] we explained that the roles of the delays $\{\tau_i\}_{i=1}^n$ and $\{\sigma_k\}_{k=1}^{\tilde{n}}$ are different from oscillational point of view.

Let us begin with two definitions before explaining briefly the situation. In the sequel we suppose that $c \in \mathbf{R}$ is a constant.

Definition 2.1. We say that the function $\varphi(t) \in C([c, \infty); \mathbf{R})$, $\varphi(t) \neq 0$, is **oscillating** when $t \rightarrow \infty$, if there exists a sequence $\{t_m\}_{m=1}^{\infty}$ such that

$$\lim_{m \rightarrow \infty} t_m = \infty \quad \text{and} \quad \varphi(t_m) = 0.$$

Definition 2.2. We say that the function $\varphi(t) \in C([c, \infty); \mathbf{R})$ is **eventually positive (respectively eventually negative)**, if there exists a constant $\tilde{c} \geq c$ such that

$$\varphi(t) > 0 \quad (\text{respectively} \quad \varphi(t) < 0), \quad \forall t \in [\tilde{c}, \infty).$$

Approximately twenty years ago Yoshida [6] obtained sufficient conditions for oscillation of an initial characteristic value problem and the next lemma was the main tool there.

Lemma 2.1. ([6]) *If there is a number $s \geq \rho$ such that*

$$(8) \quad \int_s^{s+\pi/L} F(t) \sin L(t-s) dt \leq 0,$$

then the ordinary differential inequality

$$(9) \quad z''(t) + L^2 z(t) \leq F(t)$$

has no positive solution in $(s, s + \pi/L]$.

Later Yoshida [7] dealt with another problem. There he just mentioned that he applies Lemma 2.1 immediately to the inequality

$$(10) \quad z''(t) + L^2 z(t) + \beta_1 z(t - \sigma) + \beta_2 z(t - \tau) \leq F(t),$$

where $\beta_1 \geq 0$ and $\beta_2 \geq 0$ are proper constants. He did not write anything for the distribution of the zeros of both equations

$$\begin{aligned} z''(t) + L^2 z(t) &= F(t) \quad \text{and} \\ z''(t) + L^2 z(t) + \beta_1 z(t - \sigma) + \beta_2 z(t - \tau) &= F(t) \end{aligned}$$

although he could do it in [6] and [7] respectively.

The excellent publications of Yoshida are devoted absolutely to concrete partial differential equations and the application of ordinary differential inequalities to them is not connected with the exact formulation of the conclusions for the respective ordinary differential equations.

We point out that it is very difficult to find a proper generalization of Lemma 2.1.

Vel'misov, Gârnefska and Milusheva [5] considered an equation of a pipeline under four boundary conditions and the application of Galerkin's method to these boundary problems led to the equation

$$(11) \quad A_k z''(t) + B_k z(t) + E_k z'(t - \tau_1) + F_k z'(t - \tau_2) + G_k z(t - \tau_3) = 0, \quad \text{where}$$

$$(12) \quad A_k > 0, \quad B_k \in \mathbf{R}, \quad E_k \geq 0, \quad F_k \geq 0, \quad G_k \geq 0, \quad \forall k \in \mathbf{N}.$$

In [1] we realized for the first time a combination between Galerkin's method and oscillation theory. There we considered the equation (11) under the particular case of (12), where the assumption $B_k \in \mathbf{R}$ was replaced by $B_k > 0, \forall k \in \mathbf{N}$. In this way, we succeeded to find sufficient conditions for the absence of both eventually positive and monotonically non-decreasing solutions of (11) and eventually negative and monotonically non-increasing solutions of (11).

Further, we formulated the following generalization of Lemma 2.1, which allows us to have a first derivative of the unknown function, as well as to omit the property monotonicity of the solution. There $\rho \geq 0$ is a constant.

Theorem 2.1. ([3]) *Let p_* and q_* be constants such that*

$$(13) \quad p_*, q_* \in \mathbf{R}, \quad 4q_* > p_*^2 \quad \text{and let} \quad L_* = \frac{\sqrt{4q_* - p_*^2}}{2}.$$

If there is a number $s \geq \rho$ such that

$$(14) \quad \int_s^{s+\pi/L_*} F(t) e^{\frac{p_*}{2}t} \sin L_*(t-s) dt \leq 0,$$

then the inequality

$$(15) \quad z''(t) + p_* z'(t) + q_* z(t) \leq F(t)$$

has no positive solution in $(s, s + \pi/L_*]$.

Remark 2.1. The proof of Theorem 2.1 is based on Lemma 2.1 since the function $z_1(t)$ is a solution of (14) if and only if the function $z_2(t) = z_1(t)e^{-\frac{p_*}{2}t}$ is a solution of

$$z''(t) + L_*^2 z(t) \leq F(t) e^{\frac{p_*}{2}t},$$

which is a particular case of (9).

We mention that in [2] we investigated a non-homogeneous generalization of the equation of a pipeline and there we applied the inequality

$$Az''(t) + Bz(t) + kz'(t - \tau_1) + gz'(t - \tau_2) + \beta z(t - \tau_3) \leq F(t),$$

where $A > 0$, $B > 0$, $k \geq 0$, $g \geq 0$ and $\beta > 0$

are concrete constants in [2].

Now we are ready to come back to the present equation (1) with variable coefficients. As it will become clear below, all the conclusions for (1) are based on this one for the respective inequality:

$$(16) \quad z''(t) + \sum_{i=0}^n \theta_i(t) z'(t - \tau_i) + \sum_{k=0}^{\tilde{n}} \beta_k(t) z(t - \sigma_k) + G(z''(t), z'(t), z(t)) \leq F(t).$$

Let us write the simultaneous assumptions for (1) and (16). We repeat that $\tau_i \geq 0$, $\forall i = \overline{0, n}$ and $\sigma_k \geq 0$, $\forall k = \overline{0, \tilde{n}}$ are constants again, but here we need the following new non-negative constants T , T_1 , T_2 and \tilde{T} , which are large enough. More exactly, we suppose that $\{\theta_i(t)_{i=0}^n\}$, $\{\beta_k(t)_{k=0}^{\tilde{n}}\}$ and $F(t)$ are of class $C([T, \infty); \mathbf{R})$ as well as that $G(z''(t), z'(t), z(t)) \in C([T, \infty)^3; \mathbf{R})$. Further, taking into account (3), (4) and (5), this time we assume that

$$(17) \quad \theta_i(t) \geq 0, \quad \forall t \geq T_1 \geq T \geq 0, \quad \forall i = \overline{0, n},$$

$$(18) \quad \beta_k(t) \geq 0, \quad \forall t \geq T_2 \geq T \geq 0, \quad \forall k = \overline{0, \tilde{n}},$$

$$(19) \quad \tau = \max_{0 \leq i \leq n} \tau_i, \quad \sigma = \max_{0 \leq k \leq \tilde{n}} \sigma_k \quad \text{and} \quad \tilde{\tau} = \max\{\tau, \sigma\}.$$

Further, let $\tilde{T} = \max\{T, T_1, T_2\}$

and let $g > 0$ be a positive constant such that

$$(20) \quad \begin{aligned} G(x, y, z) &\geq g^2 z, & (x, y, z) &\in \mathbf{R} \times \mathbf{R} \times [0, \infty), \\ G(x, y, z) &\leq g^2 z, & (x, y, z) &\in \mathbf{R} \times \mathbf{R} \times (-\infty, 0]. \end{aligned}$$

In fact, the notations (17) — (20) are concerned with the present continuation of the first type of oscillation results of [4]. The following lemma plays an essential role in this direction.

Lemma 2.2. *Let the assumptions (17) — (20) be fulfilled. If there is a number $s \geq \tilde{T}$ such that*

$$(21) \quad \int_s^{s+\pi/g} F(t) \sin g(t-s) dt \leq 0,$$

then the inequality (16) has no positive and monotonically non-decreasing solution in $(s - \tilde{\tau}, s + \pi/g]$.

Theorem 2.2. *Let (17) — (20) be fulfilled and let the function*

$$(22) \quad \Phi_g(s) = \int_s^{s+\pi/g} F(t) \sin g(t-s) dt$$

be oscillating. Then the equation (1) has neither eventually positive and monotonically non-decreasing solution nor eventually negative and monotonically non-increasing solution.

Proof. Since $\Phi_g(s)$ is oscillating, then

$$\exists \{s_m\}_{m=1}^\infty : \quad \lim_{m \rightarrow \infty} s_m = \infty \quad \text{and} \quad \Phi_g(s_m) = 0,$$

which guarantees that

$$\Phi_g(s_m) \leq 0 \quad \text{and} \quad \Phi_g(s_m) \geq 0.$$

Hence, we apply Lemma 2.2 to establish that the equation (1) has no eventually positive and monotonically non-decreasing solution. Similarly, we could obtain that the equation has no eventually negative and monotonically non-increasing solution.

Finally, we concentrate our attention on the equation:

$$(23) \quad z''(t) + \theta z'(t) + \sum_{k=0}^{\tilde{n}} \beta_k(t) z(t - \sigma_k) + G(z''(t), z'(t), z(t)) = F(t),$$

which is the particular case of (1), where the constant $\theta \in \mathbf{R}$ is such that (13) is satisfied in the situation:

$$(24) \quad p_* = \theta \quad \text{and} \quad q_* = g^2.$$

In other words, we suppose that

$$(25) \quad 4g^2 > \theta^2 \quad \text{and then} \quad L_* = \tilde{L}_* = \frac{\sqrt{4g^2 - \theta^2}}{2}.$$

Now we replace the pair of assumptions (19) and (20) with the following one:

$$(26) \quad \sigma = \max_{0 \leq k \leq \tilde{n}} \sigma_k \quad \text{and} \quad \tilde{T} = T_2.$$

Theorem 2.3. *Let (5), (24), (25) and (26) be satisfied and let the function*

$$\tilde{\Phi}_*(s) = \int_s^{s+\pi/\tilde{L}_*} F(t) e^{\frac{\theta t}{2}} \sin \tilde{L}_*(t-s) dt$$

be oscillating. Then every solution of the equation (23) oscillates.

Proof. This time we have that

$$\exists \{\tilde{s}_m\}_{m=1}^{\infty} : \quad \lim_{m \rightarrow \infty} \tilde{s}_m = \infty \quad \text{and} \quad \tilde{\Phi}_*(\tilde{s}_m) = 0.$$

So that, here we apply a particular case of Theorem 2.1. More exactly, here we obtain that the equation (23) has at least one zero in $(\tilde{s}_m - \sigma, \tilde{s}_m + \pi/\tilde{L}_*]$ for all $m \in \mathbf{N}$.

We mention that it is essential that $\theta \in \mathbf{R}$ is a constant in (23). In fact, if $\theta = \theta(t)$ in (23), then the respective distributions of zeros is still an open problem. The arguments are similar to the ones in Remark 2.1.

Acknowledgement

The authors would like to thank the organizers for a beautiful conference.

References

- [1] Petrova, Z. A., Application of Galerkin's method to the investigation of oscillation behaviour of two equations, Applications of Mathematics in Engineering and Economics, G. Venkov and M. Marinov, Eds., Bulvest 2000 Sofia (2003), 126-129.
- [2] Petrova, Z. A., Oscillations of an equation arising from the fluid mechanics. CFD Journal 13, 1 (2004), 13-20.
- [3] Petrova, Z. A., Oscillations of a class of sublinear and superlinear hyperbolic equations. C. R. Bulg. Acad. Sci. 58, 3, (2005), 251-256.
- [4] Petrova, Z. A., Oscillations of some equations and inequalities of second order and applications in mechanics. Applications of Mathematics in Engineering and Economics, edited by M. D. Todorov, Proc. 33rd Summer School, 224-234.
- [5] Vel'misov, P. A., Gârnefska, L. V., Milusheva, S. D., Investigation of the stability of the solution of the equation of oscillations of an axis or a plate with a delay in time of the reaction and friction forces. Applications of Mathematics in Engineering, B.I. Cheshankov and M.D. Todorov, Eds., Heron Press, Sofia (1999), 83-88.

- [6] Yoshida, N., On the zeros of solutions to nonlinear hyperbolic equations. Proc. Roy. Soc. Edinburgh Sect. A 106 (1987), 121-129.
- [7] Yoshida, N., On the zeros of solutions of hyperbolic equations of neutral type. Differential and Integral equations, 3 (1990), 155-160.

Received by the editors September 1, 2008