

ON A SCALAR CONSERVATION LAW WITH NONLINEAR DIFFUSION AND LINEAR DISPERSION IN HETEROGENEOUS MEDIA

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Abstract. We obtain the strong precompactness of a family of solutions to a suitable regularization of multidimensional scalar conservation law via vanishing nonlinear diffusion and linear dispersion. We consider the flux which depends on the time and space variables, and obtain condition $\delta = O(\varepsilon^2)$, $\varepsilon \rightarrow 0$, for the existence of a weak entropy solution. In comparison to known results for heterogeneous media (cf. [4]), our condition is weaker, thus more general.

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1. Introduction

The subject of the paper is the following Cauchy problem for multidimensional scalar conservation law:

$$(1) \quad \partial_t u(t, x) + \operatorname{div}_x f(t, x, u) = 0, \quad u(0, x) = u_0(x), \quad x \in \mathbb{R}^d, t \in \mathbb{R}^+.$$

We study the behavior of a family of solutions to a regularization of (1),

$$(2) \quad \partial_t u^{\varepsilon, \delta} + \operatorname{div}_x f(t, x, u^{\varepsilon, \delta}) = \varepsilon \sum_{j=1}^d \partial_{x_j} b_j(\nabla_x u^{\varepsilon, \delta}) + \delta \sum_{j=1}^d \partial_{x_j x_j x_j} u^{\varepsilon, \delta},$$

$$(3) \quad u(0, x) = u_0^\varepsilon(x), \quad x \in \mathbb{R}^d, \quad \varepsilon, \delta \in (0, 1), \quad \delta = \delta(\varepsilon),$$

where initial data u_0^ε from (3) converge to u_0 from (1) strongly in $L^2(\mathbb{R}^d)$ as $\varepsilon \rightarrow 0$ (all terms from (1), (2) and (3) are precisely described in the next section). In order to obtain a weak entropy solution to (1) as a limit of a subsequence of the solutions to (2)-(3), we study the precompactness properties of the family $(u^{\varepsilon, \delta})_{\varepsilon, \delta}$. The goal is to obtain optimal balance of the two parameters ε and δ .

Let us briefly recall already obtained results concerning diffusion-dispersion limits for (1). In [10], using compensated compactness arguments, the author proved that a family of solutions to KdV-Burgers equation converges to a weak

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solution to Burgers equation if diffusion and dispersion parameter are balanced in the sense that $\delta = \mathcal{O}(\varepsilon^2)$, as $\varepsilon \rightarrow 0$. Using the same methodology (in one dimensional case) with the same balance result, in [7] the diffusion-dispersion problem is solved in the case when the flux has a general homogeneous form, $f = f(u)$. Multidimensional case ($x \in \mathbb{R}^d$) is solved in [6], but with the stronger balance, $\delta = o(\varepsilon^2)$, as $\varepsilon \rightarrow 0$. More general result concerning the relative size of diffusion and dispersion parameters is made in [5]. Using the kinetic approach [9] and the averaging lemma [8, 9, 11], the author obtained in [5] the diffusion-dispersion limit with a weaker balance, $\delta = \mathcal{O}(\varepsilon^2)$, as $\varepsilon \rightarrow 0$. It is important to point out that in every of the previously mentioned works the flux which appears in the considered conservation law *does not depend on space and time explicitly*. Authors of [4], dealing with heterogeneous media for discontinuous flux in one-dimensional case, obtained stronger balance between two parameters, $\delta = o(\varepsilon^2)$, as $\varepsilon \rightarrow 0$. In order to obtain the results analogous to those from [5] (multidimensional case and optimal diffusion-dispersion ratio), similarly as in [5], we shall use the kinetic formulation of the conservation law under consideration. We will improve the balance result from [4], but with the stronger assumptions on the flux (see (H3) in the next chapter). Further improvements will be done in [1].

The paper is organized as follows. We give in Section 2 basic notations, assumptions and the statement of the main theorem. In Section 3, we prove a priori inequalities for the family $(u^{\varepsilon, \delta})_{\varepsilon, \delta}$. In Section 4 we prove the main theorem which is based on the Theorem 2.5 from [3].

2. Notations, assumptions and the main result

In the sequel, we put $|g|^2 = \sum_{i=1}^d |g_i|^2$, for a vector valued function $g = (g_1, \dots, g_d)$ defined on $\mathbb{R}^+ \times \mathbb{R}^d \times \mathbb{R}$. The derivative D_{x_i} at the point (t, x, u) , where u depends on (t, x) , is defined by $D_{x_i} g(t, x, u) = (\partial_{x_i} g(t, x, \lambda))|_{\lambda=u(t, x)}$. Derivatives ∂_{x_i} and D_{x_i} are connected by the identity $\partial_{x_i} g(t, x, u) = D_{x_i} g(t, x, u) + \partial_u g(t, x, u) \partial_{x_i} u$. For the simplicity, in the sequel we shall write u^ε instead of $u^{\varepsilon, \delta}$ and consider that $\varepsilon \in (0, 1)$. We assume that f, b and u_0 are enough regular, so that solutions u^ε , $\varepsilon \in (0, 1)$ of (2) have enough regularity, so that all formal computations below are correct, as well as that $u^\varepsilon, \partial_{x_i} u^\varepsilon$ and $\partial_{x_i x_j} u^\varepsilon$ vanish as $|x| \rightarrow \infty$. Now we list additional assumptions. For the initial data we assume that $u_0 \in L^1(\mathbb{R}^d) \cap L^2(\mathbb{R}^d)$ and $u_0^\varepsilon, \nabla u_0^\varepsilon \in H^1(\mathbb{R}^d)$. Here $u_0^\varepsilon = u_0 \star \delta_\varepsilon$, $\varepsilon \in (0, 1)$ for a suitable $(\delta_\varepsilon)_\varepsilon$ net of smooth compactly supported functions. Notice that from the last assumption $(u_0^\varepsilon)_\varepsilon$ is uniformly bounded in $L^2(\mathbb{R}^d)$. We assume that the diffusion term $b = (b_1, \dots, b_d) : \mathbb{R}^d \rightarrow \mathbb{R}^d$ fulfils the following hypotheses:

(H1) There exist positive constants C_1, C_2 such that $C_1 |\lambda|^2 \leq \lambda \cdot b(\lambda) \leq C_2 |\lambda|^2$, for all $\lambda \in \mathbb{R}^d$.

(H2) The gradient matrix $D b(\lambda)$ is a positively definite matrix uniformly in $\lambda \in \mathbb{R}^d$, i.e. there exists positive constant C_3 such that $\xi^T D b(\lambda) \xi \geq C_3 |\xi|^2$, for all $\lambda, \xi \in \mathbb{R}^d$.

We assume for the flux $f = (f_1, \dots, f_d) : \mathbb{R}^+ \times \mathbb{R}^d \times \mathbb{R} \rightarrow \mathbb{R}^d$ that $f = f(t, x, u)$ and $f_u(t, x, u)$ are continuous and that they have locally integrable derivatives

with respect to t and x . These assumptions enable us to make calculations in a priori estimates of the next section. Moreover, we assume that f fulfils the following hypotheses:

(H3) $\partial_u f \in L^\infty(\mathbb{R}^+ \times \mathbb{R}^d \times \mathbb{R})$, $D_{x_i} f_i \in L^2 \cap L^1(\mathbb{R}^+ \times \mathbb{R}^d \times \mathbb{R})$ and $|D_{x_i} f_j(t, x, v)| \leq |\zeta_{i,j}(t, x)| |v|$, for some $\zeta_{i,j} \in L^\infty(\mathbb{R}^+ \times \mathbb{R}^d)$.

The final assumption is the following nonlinearity condition **(NLC)**: For almost every $(t, x) \in \mathbb{R}^+ \times \mathbb{R}^d$ and every $\xi \in S^d$ the mapping $\lambda \mapsto \xi_0 + \sum_{k=1}^d \partial_\lambda f_i(t, x, \lambda) \xi_k$ is not identically equal to zero on any set of positive Lebesgue measure.

Our main result which will be proved in Section 4 is the following theorem.

Theorem 2.1. *Under afore listed assumptions, a family of smooth solutions $(u^{\varepsilon, \delta})_{\varepsilon, \delta}$ to Cauchy problem (2)-(3) is strongly precompact in $L^1_{\text{loc}}(\mathbb{R}^+ \times \mathbb{R}^d)$ if ε and δ from (2) are balanced in the sense that $\delta = \mathcal{O}(\varepsilon^2)$ as $\varepsilon \rightarrow 0$.*

3. A priori inequalities

In this section, we give necessary a priori inequalities.

Lemma 3.1. *Under afore listed assumptions, the family of solutions $(u^\varepsilon)_\varepsilon$ to (2)-(3) for every $t \in [0, T]$ satisfies the following inequality*

$$(4) \quad \int_{\mathbb{R}^d} |u^\varepsilon(t, x)|^2 dx + \varepsilon \int_0^t \int_{\mathbb{R}^d} |\nabla u^\varepsilon(t', x)|^2 dx dt' \leq c, \text{ for } \varepsilon < \varepsilon_0,$$

for suitable constant $c > 0$, and some $\varepsilon_0 \in (0, 1)$.

Proof: Let $\eta = \eta(u)$, $u \in \mathbb{R}$, be a smooth function. We multiply (2) by $\eta'(u^\varepsilon)$ and define $q = (q_1, \dots, q_n)$ as $q_i(t, x, u) = \int_0^u \eta'(v) \partial_v f_i(t, x, v) dv$, $i = 1, \dots, d$. Thus, (2) becomes

$$(5) \quad \begin{aligned} & \partial_t \eta(u^\varepsilon) + \text{div}_x q_i(t, x, u^\varepsilon) - \sum_{i=1}^d \int_0^{u^\varepsilon} \partial_{x_i v} f_i(t, x, v) \eta'(v) dv + \\ & \sum_{i=1}^d \eta'(u^\varepsilon) D_{x_i} f_i(t, x, u^\varepsilon) = \varepsilon \sum_{i=1}^d \partial_{x_i} (\eta'(u^\varepsilon) b_i(\nabla u^\varepsilon)) - \\ & \varepsilon \eta''(u^\varepsilon) \sum_{i=1}^d b_i(\nabla u^\varepsilon) \partial_{x_i} u^\varepsilon + \delta \sum_{i=1}^d \partial_{x_i} (\eta'(u^\varepsilon) \partial_{x_i x_i} u^\varepsilon) - \\ & \frac{\delta}{2} \eta''(u^\varepsilon) \sum_{i=1}^d \partial_{x_i} (\partial_{x_i} u^\varepsilon)^2. \end{aligned}$$

We choose here $\eta(u) = \frac{u^2}{2}$ and integrate over $[0, t] \times \mathbb{R}^d$. Taking into account

(H1) and partial integration, we obtain

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}^d} |u^\varepsilon(t, x)|^2 dx + \varepsilon C_1 \int_0^t \int_{\mathbb{R}^d} |\nabla u^\varepsilon(t', x)|^2 dx dt' \\ & \leq \frac{1}{2} \int_{\mathbb{R}^d} |u_0^\varepsilon(x)|^2 dx - \int_0^t \int_{\mathbb{R}^d} \int_0^{u^\varepsilon(t', x)} \sum_{i=1}^d D_{x_i} f_i(t', x, v) dv dx dt'. \end{aligned}$$

This and (H3) imply (4). \square

Lemma 3.2. *Under afore listed assumptions, for $|D^2 u|^2 = \sum_{i,k=1}^d |\partial_{x_i x_k} u|^2$, a family of solutions $(u^\varepsilon)_\varepsilon$ to (2)-(3) satisfies the following inequality*

$$(6) \quad \varepsilon^2 \int_{\mathbb{R}^d} |\nabla u^\varepsilon(t, x)|^2 dx + \varepsilon^3 \int_0^t \int_{\mathbb{R}^d} |D^2 u^\varepsilon(t', x)|^2 dx dt' \leq c,$$

for suitable $c > 0$, for every $t \in [0, T]$ and $\varepsilon < \varepsilon_0$.

Proof: In the sequel we will use the existence of different constants which indexes will indicate that they are new ones. As well, we will not write $\varepsilon < \varepsilon_0$ for appropriate ε_0 which can be changed. We differentiate (2) with respect to x_k and multiply the obtained expression by $\partial_{x_k} u^\varepsilon$. Then, summing expressions for $k = 1, \dots, d$, using partial integration, as well as (H2), we obtain

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}^d} \partial_t |\nabla u^\varepsilon|^2 dx - \sum_{k=1}^d \int_{\mathbb{R}^d} \nabla \partial_{x_k} u^\varepsilon \cdot (D_{x_k} f(t, x, u^\varepsilon) + \partial_u f \cdot \partial_{x_k} u^\varepsilon) dx \\ & = -\varepsilon \sum_{k=1}^d \int_{\mathbb{R}^d} (\nabla \partial_{x_k} u^\varepsilon)^T D b(\nabla u^\varepsilon) \nabla \partial_{x_k} u^\varepsilon dx \stackrel{(H2)}{\leq} -\varepsilon C_3 \sum_{k=1}^d \int_{\mathbb{R}^d} |\nabla \partial_{x_k} u^\varepsilon|^2 dx. \end{aligned}$$

Now we integrate this over $[0, t]$, use the Cauchy-Schwartz inequality, as well as the Young inequality (C_3 below is the same as above), $ab \leq \frac{C_3 \varepsilon}{2} a^2 + \frac{C_6}{\varepsilon} b^2$, $a, b \in \mathbb{R}$. Then we multiply obtained inequality by ε^2 , use inequality $(a+b)^2 \leq 2a^2 + 2b^2$ and the consequence from (4) that $\varepsilon \int_0^t \int_{\mathbb{R}^d} |\nabla u(s, x)|^2 dx ds \leq C$, $t \in [0, T]$ in order to obtain

$$\begin{aligned} & \frac{\varepsilon^2}{2} \int_{\mathbb{R}^d} |\nabla u^\varepsilon(t, x)|^2 dx + C_3 \frac{\varepsilon^3}{2} \int_{\mathbb{R}^d} \int_0^t |D^2 u^\varepsilon|^2 dx dt \leq \varepsilon^2 C_9 \int_{\mathbb{R}^d} |\nabla u_0^\varepsilon|^2 dx \\ & + \varepsilon C_{10} \int_0^t \int_{\mathbb{R}^d} \sum_{k=1}^d |D_{x_k} f(t', x, u^\varepsilon(t', x))|^2 dx dt' + C_{11} \|\partial_u f\|_{L^\infty(\mathbb{R} \times \mathbb{R}^d \times \mathbb{R})}^2 \end{aligned}$$

with appropriate constants. Taking into account (H3), (6) follows from the last inequality. \square

4. The proof of the main theorem

To prove strong precompactness of the family $(u^\varepsilon)_\varepsilon$ of solutions to (2-3), we use the averaging lemma proved in [3, Theorem 2.5]. We give its variant which is adapted to our purposes.

Theorem 4.1. *Let $(h_n)_n \subset L^2_{\text{loc}}(\mathbb{R}^N \times \mathbb{R})$ be a sequence of solutions to the following transport equation*

$$\operatorname{div}_y(F(y, \lambda)h_n(y, \lambda)) = \sum_{i=1}^d \partial_\lambda^{k_i} G_n^i(y, \lambda), \quad y \in \mathbb{R}^N, \quad \lambda \in \mathbb{R},$$

where flux $F = (F_1, \dots, F_N) \in C(\mathbb{R}^d \times \mathbb{R})$, and families $(G_n^i)_n, i = 1, \dots, N$, are strongly precompact in $H^{-1}(\mathbb{R}^N \times \mathbb{R})$. Furthermore, assume that the following non-degeneracy condition is fulfilled: For almost every $y \in \mathbb{R}^N$ and every $\xi \in S^{N-1}$ the mapping

$$\lambda \mapsto \sum_{k=1}^N F_k(y, \lambda)\xi_k$$

is not identically equal to zero on any set of positive Lebesgue measure.

Then for every $\rho \in C_0^\infty(\mathbb{R})$ the sequence $(\int_{\mathbb{R}} h_n(x, \lambda)\rho(\lambda)d\lambda)_n$ is strongly precompact in $L^1_{\text{loc}}(\mathbb{R}^d \times \mathbb{R})$.

Proof of the Theorem 2.1: Let $\eta \in C_0^\infty(\mathbb{R})$ and

$$h_\varepsilon(t, x, \lambda) = \begin{cases} 1, & \text{for } 0 < \lambda \leq u^\varepsilon(t, x), \quad (t, x) \in \Pi, \\ -1, & \text{for } 0 > \lambda \geq u^\varepsilon(t, x), \quad (t, x) \in \Pi, \\ 0, & \text{otherwise,} \end{cases}$$

where $\Pi = (0, T) \times \mathbb{R}^d$. Let $\varphi \in C_0^\infty(\Pi)$. We rewrite (5) as

$$\begin{aligned} (7) \quad & - \int_{\Pi \times \mathbb{R}} h_\varepsilon(t, x, \lambda)\eta'(\lambda)\varphi_t(t, x) d\lambda dx dt \\ & - \sum_{i=1}^d \int_{\Pi \times \mathbb{R}} h_\varepsilon(t, x, \lambda)\partial_\lambda f_i(t, x, \lambda)\eta'(\lambda)\varphi_{x_i}(t, x) d\lambda dx dt \\ & + \sum_{i=1}^d \int_{\Pi \times \mathbb{R}} h_\varepsilon(t, x, \lambda)\partial_{x_i \lambda} f_i(t, x, \lambda)\eta''(\lambda)\varphi(t, x) d\lambda dx dt \\ & = - \int_{\Pi} \sum_{i=1}^d (\varepsilon b_i(\nabla u^\varepsilon) + \delta \partial_{x_i x_i} u^\varepsilon) \eta'(u^\varepsilon) \varphi_{x_i}(t, x) dx dt \\ & - \sum_{i=1}^d \int_{\Pi} (\varepsilon b_i(\nabla u^\varepsilon) u^\varepsilon_{x_i} + \delta u^\varepsilon_{x_i} \partial_{x_i x_i} u^\varepsilon) \eta''(u^\varepsilon) \varphi(t, x) dx dt. \end{aligned}$$

As in [5], we represent equation (7) as an equation in $\mathcal{D}'(\Pi \times \mathbb{R})$. With an abuse of notation (see notation in Section 2) we put $H_i^\varepsilon(t, x) = \varepsilon b_i(\nabla u^\varepsilon)$, $\bar{H}_i^\varepsilon(t, x) =$

$\delta \partial_{x_i x_i} u^\varepsilon$, $G_i^\varepsilon(t, x) = \varepsilon b_i(\nabla u^\varepsilon) u_{x_i}^\varepsilon$, $\bar{G}_i^\varepsilon(t, x) = \delta u_{x_i}^\varepsilon \partial_{x_i x_i} u^\varepsilon$, and note that the nets $H_i^\varepsilon, \bar{H}_i^\varepsilon, G_i^\varepsilon(t, x), \bar{G}_i^\varepsilon$ are uniformly bounded in $L^1_{\text{loc}}(\Pi \times \mathbb{R})$ (cf. (H1)-(H3) and Lemmas 3.1-3.2). Let $\delta(\lambda - u)$ be a Dirac delta function defined by $\langle \delta(\lambda - u), \eta(\lambda) \rangle = \eta(u)$. Then $m_i^\varepsilon = \delta(\lambda - u^\varepsilon) G_i^\varepsilon$, $k_i^\varepsilon = \delta(\lambda - u^\varepsilon) \bar{G}_i^\varepsilon$, $\pi_i^\varepsilon = \delta(\lambda - u^\varepsilon) H_i^\varepsilon$ and $\bar{\pi}_i^\varepsilon = \delta(\lambda - u^\varepsilon) \bar{H}_i^\varepsilon$, $i = 1, \dots, d$, $\varepsilon < 1$, are defined as distributions in $\mathcal{D}'(\Pi \times \mathbb{R})$ via the following tensor products:

$$(8) \quad \begin{aligned} \langle m_i^\varepsilon, \varphi \otimes \eta' \rangle &= \int_{\Pi} G_i^\varepsilon(t, x) \varphi(t, x) \eta'(u^\varepsilon(t, x)) dx dt, \\ \langle k_i^\varepsilon, \varphi \otimes \eta' \rangle &= \int_{\Pi} \bar{G}_i^\varepsilon(t, x) \varphi(t, x) \eta'(u^\varepsilon(t, x)) dx dt, \\ \langle \pi_i^\varepsilon, \varphi \otimes \eta' \rangle &= \int_{\Pi} H_i^\varepsilon(t, x) \varphi(t, x) \eta'(u^\varepsilon(t, x)) dx dt, \\ \langle \bar{\pi}_i^\varepsilon, \varphi \otimes \eta' \rangle &= \int_{\Pi} \bar{H}_i^\varepsilon(t, x) \varphi(t, x) \eta'(u^\varepsilon(t, x)) dx dt. \end{aligned}$$

The mapping $\eta(\lambda) \mapsto \langle \delta(\lambda - u^\varepsilon) G_i^\varepsilon(t, x), \eta(\lambda) \rangle = \langle \delta(\lambda - u^\varepsilon) \varepsilon b_i(\nabla u^\varepsilon) u_{x_i}^\varepsilon, \eta(\lambda) \rangle = \varepsilon u^\varepsilon b_i(\nabla u^\varepsilon) \partial_x \eta(u^\varepsilon(t, x))$, with values in $\mathcal{D}'(\Pi)$, is continuous, so (8) holds and we can prove other identities in the same way. Thus, (7) can be rewritten as equation in $\mathcal{D}'(\Pi \times \mathbb{R})$ as follows

$$(9) \quad \begin{aligned} \partial_t h_\varepsilon(t, x, \lambda) + \sum_{i=1}^d \partial_{x_i} (h_\varepsilon(t, x, \lambda) \partial_\lambda f_i(t, x, \lambda)) = \\ \sum_{i=1}^d \partial_\lambda (h_\varepsilon(t, x, \lambda) \partial_{x_i} f_i(t, x, \lambda)) + \sum_{i=1}^d (\partial_{x_i} (\pi_i^\varepsilon + \bar{\pi}_i^\varepsilon) + \partial_\lambda (m_i^\varepsilon + k_i^\varepsilon)). \end{aligned}$$

Now we estimate terms on the right-hand side of (9). By Lemmas 3.1-3.2 and (H1) (as in [5]), we obtain the following results ((10) and (11)):

$$(10) \quad \pi_i^\varepsilon = \bar{g}_i^\varepsilon + \partial_\lambda g_i^\varepsilon, \quad \bar{\pi}_i^\varepsilon = \bar{p}_i^\varepsilon + \partial_\lambda p_i^\varepsilon, \quad i = 1, \dots, d,$$

with $\bar{g}_i^\varepsilon, g_i^\varepsilon \rightarrow 0$ and $\bar{p}_i^\varepsilon, p_i^\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0$ in $L^2(\Pi \times \mathbb{R})$;

$$(11) \quad (m_i^\varepsilon)_\varepsilon, (k_i^\varepsilon)_\varepsilon \text{ lie in a bounded set of } \mathcal{M}(\Pi \times \mathbb{R}), \text{ for every } i = 1, \dots, d,$$

where $\mathcal{M}(\Pi \times \mathbb{R})$ stands for the space of bounded measures. The proof is technical (cf. [5]) and will be omitted. Consider now the remaining term on the right hand side of (9). Denote by $\Pi_i^\varepsilon(t, x, \lambda) = \partial_\lambda (h_\varepsilon(t, x, \lambda) \partial_{x_i} f_i(t, x, \lambda))$, $(t, x, \lambda) \in \Pi \times \mathbb{R}$, $i = 1, \dots, d$. Let $\theta(t, x, \lambda) \in C_0^\infty((0, T) \times \mathbb{R}^d \times \mathbb{R})$ and $i = 1, \dots, d$. Then,

$$\begin{aligned} \langle \Pi_i^\varepsilon, \theta \rangle &= \left| \int_{\Pi \times \mathbb{R}} h_\varepsilon(t, x, \lambda) \partial_{x_i} f_i(t, x, \lambda) \theta_\lambda(t, x, \lambda) dt dx d\lambda \right| \\ &\leq \|\theta_\lambda\|_{C^0(\Pi \times \mathbb{R})} \int_{\text{supp} \theta} |\partial_\lambda f_i(t, x, \lambda)| dt dx d\lambda \leq C \|\theta_\lambda\|_{C^0(\Pi \times \mathbb{R})}, \end{aligned}$$

where C is a constant depending only on the support of a test function θ . Thus, for every $i = 1, \dots, d$ the family $(\Pi_i^\varepsilon)_\varepsilon$ lies in a locally bounded subset of the space of bounded measures $\mathcal{M}(\Pi \times \mathbb{R})$. Knowing that every sequence of measures bounded in $\mathcal{M}(\Pi \times \mathbb{R})$ is precompact in $H^{-1}(\Pi \times \mathbb{R})$ (cf. [2] Theorem 5), we can apply Theorem 4.1 for the net $(h_\varepsilon)_\varepsilon$ and conclude that a subsequence $(h_k)_k$ of $(h_\varepsilon)_\varepsilon$ satisfies

$$(12) \quad \left(\int_{-R}^R h_k(t, x, \lambda) d\lambda \right)_{k \in \mathbb{N}} \text{ is convergent in } L^1_{\text{loc}}(\mathbb{R}^+ \times \mathbb{R}^d),$$

for every $R \in \mathbb{N}$. Furthermore,

$$(13) \quad \begin{aligned} \left| u^\varepsilon - \int_{-R}^R h_\varepsilon(t, x, \lambda) d\lambda \right| &= \left| \int_\lambda h_\varepsilon(t, x, \lambda) d\lambda - \int_{-R}^R h_\varepsilon(t, x, \lambda) d\lambda \right| \\ &= \left| \int_R^\infty h_\varepsilon(t, x, \lambda) d\lambda + \int_{-\infty}^{-R} h_\varepsilon(t, x, \lambda) d\lambda \right| \\ &= H(u^\varepsilon - R)(u^\varepsilon - R) + H(-u^\varepsilon - R)(-u^\varepsilon - R). \end{aligned}$$

Thus by Lemma 3.1, we have that there exists constant $K_1 > 0$, so that

$$(14) \quad \begin{aligned} &\int_0^t \int_{\mathbb{R}} [H(u^\varepsilon - R)(u^\varepsilon - R) + H(-u^\varepsilon - R)(-u^\varepsilon - R)] dx dt \\ &\leq \int_{|u^\varepsilon| > R} |u^\varepsilon| dx dt \leq \frac{1}{R} \int_0^t \int_x |u^\varepsilon|^2 dx dt \leq \frac{K_1}{R}, \end{aligned}$$

since $\int_{|u^\varepsilon| > R} R |u^\varepsilon| dx dt \leq \int_{|u^\varepsilon| > R} |u^\varepsilon|^2 dx dt < \tilde{K}_1$. Therefore, from (13) and (14) it follows

$$(15) \quad \int_0^t \int_{\mathbb{R}} \left| u^\varepsilon - \int_{-R}^R h_\varepsilon(t, x, \lambda) d\lambda \right| dt dx \leq \frac{K_1}{R}$$

Now by (15) it is easy to prove that $(u^k)_k$ (where the indexing is taken from (12)) is a Cauchy sequence in $L^1_{\text{loc}}(\Pi)$. Indeed, for every compact set $K \subset\subset \Pi$, we have

$$\begin{aligned} &\int_K |u^{k_1} - u^{k_2}| dx dt \\ &\leq \int_K \left| u^{k_1} - \int_{-R}^R h_{k_1}(t, x, \lambda) d\lambda \right| dx dt + \int_K \left| u^{k_2} - \int_{-R}^R h_{k_2}(t, x, \lambda) d\lambda \right| dx dt \\ &+ \int_K \left| \int_{-R}^R h_{k_1}(t, x, \lambda) d\lambda - \int_{-R}^R h_{k_2}(t, x, \lambda) d\lambda \right| dx dt \leq \frac{2K_1}{R} + \gamma(k_1, k_2), \end{aligned}$$

where $\frac{2K_1}{R}$ appears due to (15), and γ is a function tending to zero as $k_i \rightarrow \infty$, $i = 1, 2$, because $(h_k)_k$ is convergent in $L^1_{\text{loc}}(\Pi \times \mathbb{R})$. Thus, we see that the subsequence $(u^k)_k$ of $(u^\varepsilon)_\varepsilon$ is the Cauchy sequence in $L^1_{\text{loc}}(\Pi)$. This implies that the family $(u^\varepsilon)_\varepsilon$ is precompact in $L^1_{\text{loc}}(\Pi)$. \square

Remark 4.1. Notice that if $\delta = o(\varepsilon^2)$, $\varepsilon \rightarrow 0$, then $(u^k)_k$ tends to a unique entropy solution to (1). The proof is analogous to the one from [6].

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